# On a class of Lorentzian paracontact metric manifolds 

K. L. Sai Prasad*<br>Department of Mathematics<br>Gayatri Vidya Parishad College of Engineering for Women<br>Kommadi, Visakhapatnam, 530048<br>India<br>klsprasad@gvpcew.ac.in<br>\section*{S. Sunitha Devi}<br>Department of Mathematics<br>Guru Nanak University<br>Hyderabad-501506<br>INDIA<br>sunithamallakula@yahoo.com<br>G.V.S.R. Deekshitulu<br>Department of Mathematics<br>Jawaharlal Nehru Technological University<br>Kakinada, 533003<br>India<br>dixitgvsr@yahoo.co.in


#### Abstract

In this present paper, we consider a class of Lorentzian almost paracontact metric manifolds namely Lorentzian para-Kenmotsu (briefly LP-Kenmotsu) manifolds admitting a pseudo-projective curvature tensor $\bar{W}(X, Y)$. We study and have shown that the scalar curvature of Lorentzian para-Kenmotsu manifold is constant if and only if the time like vector field $\xi$ is harmonic, whenever the $L P$-Kenmotsu manifold satisfying $R(X, Y) \cdot \bar{W}=0$ is not an Einstein manifold. Further we have shown that Lorentzian para-Kenmotsu manifolds admitting an irrotational pseudo-projective curvature tensor and a conservative pseudo-projective curvature tensor are an Einstein manifolds of constant scalar curvature. At the end, we construct an example of a 3-dimensional $L P$-Kenmotsu manifold admitting a pseudo-projective curvature tensor which verifies the results discussed in the present work.


Keywords: Lorentzian para-Kenmotsu manifolds, pseudo-projective curvature tensor, harmonic vector field, irrotational and conservative vector fields.

## 1. Introduction

In 1989, Matsumoto [8] introduced the notion of Lorentzian paracontact metric manifolds and defined Lorentzian para-Sasakian (LP-Sasakian) manifolds, which are regarded as a special kind of these Lorentzian paracontact manifolds. Further, these manifolds have been widely studied by many geometers such as
*. Corresponding author

De, Matsumoto and Shaikh [7], Matsumoto and Mihai [9], Mihai and Rosca [10], Mihai, Shaikh and De [11], Venkatesha and Bagewadi [16], Venkatesha, Pradeep Kumar and Bagewadi [17] and obtained several results on these manifolds.

In 1995, Sinha and Sai Prasad [15] defined a class of almost paracontact metric manifolds namely para-Kenmotsu (briefly $P$-Kenmotsu) and special paraKenmotsu (briefly $S P$-Kenmotsu) manifolds in similar to $P$-Sasakian and $S P$ Sasakian manifolds. In 2018, Abdul Haseeb and Rajendra Prasad defined a class of Lorentzian almost paracontact metric manifolds namely Lorentzian para-Kenmotsu (briefly $L P$-Kenmotsu) manifolds [1] and they studied $\phi$-semisymmetric $L P$-Kenmotsu manifolds with a quarter-symmetric non-metric connection admitting Ricci solitons [13].

On the other hand, in 1970 [12], Pokhariyal and Mishra introduced new tensor fields, called the Weyl-projective curvature tensor $W_{2}$ of type $(1,3)$ and the tensor field $E$ on a Riemannian manifold. In our earlier work, we consider $L P$-Kenmotsu manifolds admitting the Weyl-projective curvature tensor $W_{2}$ and shown that these manifolds admitting a Weyl-flat projective curvature tensor, an irrotational Weyl-projective curvature tensor and a conservative Weyl-projective curvature tensor are an Einstein manifolds of constant scalar curvature [14].

The idea of Weyl-projective curvature tensor has been extended by Bhagawat Prasad [6], and in 2002 he defined the pseudo-projective curvature tensor $\bar{W}$ on a Riemannian manifold $M_{n}$ of dimension $n$ as:

$$
\begin{align*}
\bar{W}(X, Y) Z & =a R(X, Y) Z+b[S(Y, Z) X-S(X, Z) Y] \\
& -\frac{r}{n}\left[\frac{a}{n-1}+b\right][g(Y, Z) X-g(X, Z) Y] \tag{1}
\end{align*}
$$

where $a$ and $b$ are constants such that $a, b \neq 0$. In the above expression $R(X, Y)$ is known to be the Riemannian curvature tensor, $S$ is the Ricci tensor and $r$ is the scalar curvature with respect to the Levi-Civita connection.

The pseudo-projective curvature tensor on a Riemannian manifold was widely studied by Bagewadi et al., [2], Bagewadi and Venkatesha [3, 4] and by many geometers. In 2008, Bagewadi et al., [5] have extended these concepts to Lorentzian paracontact structures and studied $L P$-Sasakian manifolds admitting this tensor field of particular type. They have shown that the $L P$-Sasakian manifold is an Einstein manifold if the pseudo projective curvature tensor admitted by the manifold is irrotational.

Motivated by these studies, in the present paper, we explore the geometrical significance of $L P$-Kenmotsu manifolds admitting the pseudo-projective curvature tensor. The present paper is organized as follows: Section 2 is equipped with some prerequisites about Lorentzian para-Kenmotsu manifolds. In section 3 , we consider Lorentzian para-Kenmotsu manifolds admitting $R(X, Y) \cdot \bar{W}=0$ and shown that it is an $\eta$-Einstein manifold of constant scalar curvature $n(n-1)$. As a special case, we have shown that the scalar curvature of Lorentzian paraKenmotsu manifold is constant if and only if the time like vector field $\xi$ is
harmonic, whenever the $L P$-Kenmotsu manifold satisfying $R(X, Y) \cdot \bar{W}=0$ is not an Einstein manifold.

In the sections 4 and 5 , we study geometrical properties of these manifolds, and in particular, we have shown that Lorentzian para-Kenmotsu manifolds admitting an irrotational pseudo-projective curvature tensor and a conservative pseudo-projective curvature tensor are an Einstein manifolds of constant scalar curvature. Finally, in section 6 , we construct an example of a 3 -dimensional $L P$ Kenmotsu manifold admitting pseudo-projective curvature tensor which verifies the results discussed in the present work.

## 2. Preliminaries

An $n$-dimensional differentiable manifold $M_{n}$ admitting a $(1,1)$ tensor field $\phi$, contravariant vector field $\xi$, a 1-form $\eta$ and the Lorentzian metric $g(X, Y)$ satisfying

$$
\begin{equation*}
\phi^{2} X=X+\eta(X) \xi, \quad g(\phi X, \phi Y)=g(X, Y)+\eta(X) \eta(Y) \tag{2}
\end{equation*}
$$

and

$$
\begin{equation*}
\eta(\xi)=-1, \quad \phi \xi=0, \quad \eta(\phi X)=0, \quad g(X, \xi)=\eta(X), \operatorname{rank} \phi=n-1 \tag{3}
\end{equation*}
$$

for arbitrary vector fields $X, Y$ on $M_{n}$, is called Lorentzian almost paracontact manifold [8].

In a Lorentzian almost paracontact manifold, for any vector fields $X, Y$ on $M_{n}$, we have

$$
\begin{equation*}
\Phi(X, Y)=\Phi(Y, X) \tag{4}
\end{equation*}
$$

where $\Phi(X, Y)=g(X, \phi Y)$ is a symmetric $(0,2)$ tensor field.
A Lorentzian almost paracontact manifold $M_{n}$ is called Lorentzian paraKenmotsu manifold if [1]

$$
\begin{equation*}
\left(\nabla_{X} \phi\right) Y=-g(\phi X, Y) \xi-\eta(Y) \phi X \tag{5}
\end{equation*}
$$

for all $X, Y \in \chi\left(M_{n}\right)$, where $\chi\left(M_{n}\right)$ is the set of all differentiable vector fields on $M_{n}$ and $\nabla$ is known to be the operator of covariant differentiation with respect to the Lorentzian metric $g$.

In a Lorentzian para-Kenmotsu manifold, the following relations hold good [1]:

$$
\begin{align*}
& \nabla_{X} \xi=-\phi^{2} X=-X-\eta(X) \xi  \tag{6}\\
& \left(\nabla_{X} \eta\right) Y=-g(X, Y)-\eta(X) \eta(Y)  \tag{7}\\
& g(R(X, Y) Z, \xi)=\eta(R(X, Y) Z)=g(Y, Z) \eta(X)-g(X, Z) \eta(Y)  \tag{8}\\
& R(\xi, X) Y=g(X, Y) \xi-\eta(Y) X  \tag{9}\\
& R(X, Y) \xi=\eta(Y) X-\eta(X) Y  \tag{10}\\
& S(X, \xi)=(n-1) \eta(X) \tag{11}
\end{align*}
$$

and

$$
\begin{equation*}
S(\phi X, \phi Y)=S(X, Y)+(n-1) \eta(X) \eta(Y) \tag{12}
\end{equation*}
$$

for any vector fields $X, Y$ and $Z$ on $M_{n}$.
By putting $Z=\xi$ in (1) and on simplification by using (3), (10) and (11), we get

$$
\begin{equation*}
\bar{W}(X, Y) \xi=[a+(n-1) b]\left[1-\frac{r}{n(n-1)}\right][\eta(Y) X-\eta(X) Y] \tag{13}
\end{equation*}
$$

The above expression can be written as:

$$
\begin{equation*}
\bar{W}(X, Y) \xi=k[\eta(Y) X-\eta(X) Y] \tag{14}
\end{equation*}
$$

where

$$
k=[a+(n-1) b]\left[1-\frac{r}{n(n-1)}\right]
$$

## 3. Pseudo-projective semisymmetric $L P$-Kenmotsu manifolds

Let us consider an $L P$-Kenmotsu manifold $\left(M_{n}, g\right)$ satisfying the condition $[3,4]$

$$
\begin{equation*}
R(X, Y) \cdot \bar{W}=0 \tag{15}
\end{equation*}
$$

for any arbitrary vector fields $X, Y$ on $M_{n}$. Then the manifold $M_{n}$ is called as the pseudo-projective semisymmetric $L P$-Kenmotsu manifold (or) simply called as $\bar{W}$-semisymmetric $L P$-Kenmotsu manifold.

On the other hand, we have

$$
\begin{align*}
(R(X, Y) \cdot \bar{W})(U, V) Z= & R(X, Y) \bar{W}(U, V) Z-\bar{W}(R(X, Y) U, V) Z \\
& -\bar{W}(U, R(X, Y) V) Z-\bar{W}(U, V) R(X, Y) Z \tag{16}
\end{align*}
$$

for any vector fields $X, Y, Z, U, V \in \chi\left(M_{n}\right)$. Then, from (15) and (16), we have

$$
\begin{align*}
& g(R(\xi, Y) \bar{W}(U, V) Z, \xi)-g(\bar{W}(R(\xi, Y) U, V) Z, \xi) \\
& -g(\bar{W}(U, R(\xi, Y) V) Z, \xi)-g(\bar{W}(U, V)(R(\xi, Y) Z, \xi))=0 \tag{17}
\end{align*}
$$

By virtue of (8) and (9), we get each term of the above expression as:
(a) $g(R(\xi, Y) \bar{W}(U, V) Z, \xi)=-\bar{W}^{\prime}(U, V, Z, Y)-\eta(Y) \eta(\bar{W}(U, V) Z)$,
(b) $g(\bar{W}(R(\xi, Y) U, V) Z, \xi)=g(Y, U) \eta(\bar{W}(\xi, V) Z)-\eta(U) \eta(\bar{W}(Y, V) Z)$,
(c) $g(\bar{W}(U, R(\xi, Y) V) Z, \xi)=\eta(V) \eta(\bar{W}(U, Y) Z)-g(Y, V) \eta(\bar{W}(U, \xi) Z)$,
(d) $g(\bar{W}(U, V)(R(\xi, Y) Z, \xi))=g(Y, Z) \eta(\bar{W}(U, V) \xi)$

$$
-\eta(Z) \eta(\bar{W}(U, V) Y)=0
$$

for arbitrary vector fields $U, V, Z, Y \in \chi\left(M_{n}\right)$, where

$$
\bar{W}^{\prime}(U, V, Z, Y)=g(\bar{W}(U, V) Z, Y)
$$

By substituting the above values from (18) in (17), we obtain that

$$
\begin{align*}
& -\bar{W}^{\prime}(U, V, Z, Y)-\eta(Y) \eta(\bar{W}(U, V) Z)-g(Y, U) \eta(\bar{W}(\xi, V) Z) \\
& +\eta(U) \eta(\bar{W}(Y, V) Z)-g(Y, V) \eta(\bar{W}(U, \xi) Z)+\eta(V) \eta(\bar{W}(U, Y) Z)  \tag{19}\\
& -g(Y, Z) \eta(\bar{W}(U, V) \xi)+\eta(Z) \eta(\bar{W}(U, V) Y)=0
\end{align*}
$$

Clearly it follows from (13) that

$$
\begin{equation*}
\eta(\bar{W}(U, V) \xi)=0 \tag{20}
\end{equation*}
$$

where $U, V \in \chi\left(M_{n}\right)$.
Now, by using (20) in (19), we get

$$
\begin{align*}
& -\bar{W}^{\prime}(U, V, Z, Y)-\eta(Y) \eta(\bar{W}(U, V) Z)-g(Y, U) \eta(\bar{W}(\xi, V) Z) \\
& +\eta(U) \eta(\bar{W}(Y, V) Z)-g(Y, V) \eta(\bar{W}(U, \xi) Z)+\eta(V) \eta(\bar{W}(U, Y) Z)  \tag{21}\\
& +\eta(Z) \eta(\bar{W}(U, V) Y)=0
\end{align*}
$$

for any vector fields $U, V, Z, Y \in \chi\left(M_{n}\right)$.
Let $\left\{e_{i}=1: i=1,2,3, \cdots, n\right\}$ be an orthonormal basis of the tangent space at any point of the manifold.

By putting $U=Y=e_{i}$ in (21) we get that

$$
\begin{align*}
& \bar{W}^{\prime}\left(e_{i}, V, Z, e_{i}\right)+g\left(e_{i}, e_{i}\right) \eta(\bar{W}(\xi, V) Z)+\eta(V) \eta\left(\bar{W}\left(e_{i}, \xi\right) Z\right) \\
& -\eta(V) \eta\left(\bar{W}\left(e_{i}, e_{i}\right) Z\right)-\eta(Z) \eta\left(\bar{W}\left(e_{i}, V\right) e_{i}\right)=0 \tag{22}
\end{align*}
$$

On further simplification of the above equation, we have

$$
\begin{equation*}
\bar{W}^{\prime}\left(e_{i}, V, Z, e_{i}\right)+g\left(e_{i}, e_{i}\right) \eta(\bar{W}(\xi, V) Z)-\eta(Z) \eta\left(\bar{W}\left(e_{i}, V\right) e_{i}\right)=0 \tag{23}
\end{equation*}
$$

as $\eta\left(\bar{W}\left(e_{i}, e_{i}\right) Z\right)=0$.
Now, by taking summation over $1 \leq i \leq n$ in (23), we get
(24) $\sum_{i=1}^{n} \epsilon_{i} \bar{W}^{\prime}\left(e_{i}, V, Z, e_{i}\right)+(n-1) \eta(\bar{W}(\xi, V) Z)-\eta(Z) \sum_{i=1}^{n} \epsilon_{i} \eta\left(\bar{W}\left(e_{i}, V\right) e_{i}\right)=0$,
where $\epsilon_{i}=g\left(e_{i}, e_{i}\right)$.

Now, by using (9) and (1), the terms of the above expression are obtained as:

$$
\begin{align*}
& \text { (a) } \sum_{i=1}^{n} \epsilon_{i} \bar{W}^{\prime}\left(e_{i}, V, Z, e_{i}\right)=[a+(n-1) b] S(V, Z) \\
& -\frac{r}{n}[a+(n-1) b] g(V, Z), \\
& \text { (b) } \eta(\bar{W}(\xi, V) Z)=\left[-a+\frac{r}{n}\left(\frac{a}{n-1}+b\right)\right][g(V, Z)+\eta(V) \eta(Z)  \tag{25}\\
& -b S(V, Z)-b(n-1) \eta(V) \eta(Z)], \\
& \text { (c) } \sum_{i=1}^{n} \epsilon_{i} \eta\left(\bar{W}\left(e_{i}, V\right) e_{i}\right)=[a-b]\left[\frac{r}{n}-(n-1)\right] \eta(V) .
\end{align*}
$$

By substituting the above values in (24), we get

$$
\begin{equation*}
a S(V, Z)-a(n-1) g(V, Z)+b[r-n(n-1)] \eta(V) \eta(Z)=0, \tag{26}
\end{equation*}
$$

which can be written as

$$
\begin{equation*}
S(V, Z)=(n-1) g(V, Z)-\frac{b}{a}[r-n(n-1)] \eta(V) \eta(Z), \tag{27}
\end{equation*}
$$

for any vector fields $V$ and $Z$ on $M_{n}$. Thus, we have the following assertion.
Theorem 3.1. An LP-Kenmotsu manifold $\left(M_{n}, g\right)$ satisfying the condition $R(X, Y) \cdot \bar{W}=0$ is an $\eta$-Einstein manifold.

Further, by taking $Z=\xi$ in (27) and on simplification by using (3) and (11), we obtain that $r=n(n-1)$ and this leads to the following assertion.

Corollary 3.1. An LP-Kenmotsu manifold $\left(M_{n}, g\right)$ satisfying the condition $R(X, Y) \cdot \bar{W}=0$ is of constant scalar curvature $n(n-1)$.

Now, let us consider a special case in which the $L P$-Kenmotsu manifold admitting $R(X, Y) \cdot \bar{W}=0$ is not an Einstein manifold. Then, from (27) it follows that $r \neq n(n-1)$; otherwise it is an Einstein manifold.

On differentiating (27) covariantly along $X$ and then on using (7), we get
$\left(\nabla_{X} S\right)(V, Z)=-\frac{b}{a} d r(X) \eta(V) \eta(Z)$

$$
\begin{equation*}
-\frac{b}{a}[r-n(n-1)][g(X, V) \eta(Z)+g(X, Z) \eta(V)+2 \eta(X) \eta(V) \eta(Z)] . \tag{28}
\end{equation*}
$$

By putting $X=Z=e_{i}$ in the above expression and on taking summation for $1 \leq i \leq n$, we obtain that

$$
\begin{equation*}
d r(V)=\frac{b}{a}[d r(\xi)-[r-n(n-1) \Psi]] \eta(V) \tag{29}
\end{equation*}
$$

where $\Psi=1+\sum_{i=1}^{n} \epsilon_{i} g\left(e_{i}, e_{i}\right)$.

On replacing $V$ with $\xi$ in the above expression (29), we get that

$$
\begin{equation*}
d r(\xi)=\frac{b}{a+b}[r-n(n-1)] \Psi \tag{30}
\end{equation*}
$$

From (29) and (30) we obtain

$$
\begin{equation*}
d r(V)=\frac{b}{a+b}[n(n-1)-r] \Psi \eta(V) \tag{31}
\end{equation*}
$$

If $r$ is constant then (31) yields either $r=n(n-1)$ or $\Psi=0$. But as $r \neq n(n-1)$, we must have $\Psi=0$, which means that the vector field $\xi$ is harmonic.

Again, if $\Psi=0$, then from (31) it follows that $r$ is constant. Thus we can state the following:

Theorem 3.2. If the LP-Kenmotsu manifold admitting the condition $R(X, Y)$. $\bar{W}=0$ is not an Einstein manifold, then the scalar curvature of the manifold is constant if and only if the time like vector field $\xi$ is harmonic.

## 4. Irrotational pseudo-projective curvature tensor in $L P$-Kenmotsu manifolds

Definition 4.1. The rotation (curl) of pseudo-projective curvature tensor $\bar{W}$ on a Riemannian manifold is given by [2]

$$
\begin{align*}
\operatorname{Rot} \bar{W} & =\left(\nabla_{U} \bar{W}\right)(X, Y) Z+\left(\nabla_{X} \bar{W}\right)(U, Y) Z \\
& +\left(\nabla_{Y} \bar{W}\right)(X, U) Z-\left(\nabla_{Z} \bar{W}\right)(X, Y) U, \tag{32}
\end{align*}
$$

for all $X, Y, U, Z \in \chi\left(M_{n}\right)$.
In virtue of Bianchi's second identity, we have

$$
\begin{equation*}
\left(\nabla_{U} \bar{W}\right)(X, Y) Z+\left(\nabla_{X} \bar{W}\right)(U, Y) Z+\left(\nabla_{Y} \bar{W}\right)(X, U) Z=0 \tag{33}
\end{equation*}
$$

Therefore, (32) reduces to

$$
\begin{equation*}
\operatorname{Rot} \bar{W}=-\left(\nabla_{Z} \bar{W}\right)(X, Y) U \tag{34}
\end{equation*}
$$

for all $X, Y, U, Z \in \chi\left(M_{n}\right)$.
Now, let us suppose that the pseudo-projective curvature tensor is irrotational. Then curl $\bar{W}=0$ and so by (34) we get

$$
-\left(\nabla_{Z} \bar{W}\right)(X, Y) U=0
$$

which implies the following:

$$
\begin{equation*}
\nabla_{Z}(\bar{W}(X, Y) U)=\bar{W}\left(\nabla_{Z} X, Y\right)+\bar{W}\left(X, \nabla_{Z} Y\right) U+\bar{W}(X, Y) \nabla_{Z} U \tag{35}
\end{equation*}
$$

for any arbitrary vector fields $X, Y, U, Z \in \chi\left(M_{n}\right)$.

By replacing $U=\xi$ in (35), we have

$$
\begin{equation*}
\nabla_{Z}(\bar{W}(X, Y) \xi)=\bar{W}\left(\nabla_{Z} X, Y\right) \xi+\bar{W}\left(X, \nabla_{Z} Y\right) \xi+\bar{W}(X, Y) \nabla_{Z} \xi \tag{36}
\end{equation*}
$$

Using (14) in (36) and on simplifying by making use of (6), we get

$$
\begin{equation*}
\bar{W}(X, Y) \phi^{2} Z=-k[g(Z, \phi Y) X-g(Z, \phi X) Y] \tag{37}
\end{equation*}
$$

which on further simplification by using (2) and (14), we get

$$
\begin{equation*}
\bar{W}(X, Y) Z=k[g(Y, Z) X-g(X, Z) Y] \tag{38}
\end{equation*}
$$

for any vector fields $X, Y, Z \in \chi\left(M_{n}\right)$. Thus, we can state:
Lemma 4.1. If the pseudo-projective curvature tensor $\bar{W}$ in an LP-Kenmotsu manifold is irrotational, then $\bar{W}$ is given by the expression (38).

Further, in view of (1) and (38) we get

$$
\begin{align*}
a R(X, Y) W & =[a+(n-1) b][g(Y, W) X-g(X, W) Y] \\
& -b[S(Y, W) X-S(X, W) Y] \tag{39}
\end{align*}
$$

where $X, Y, Z \in \chi\left(M_{n}\right)$.
Let $\left\{e_{i}=1: i=1,2,3, \cdots, n\right\}$ be an orthonormal basis of the tangent space at any point of the manifold. Then, by putting $Y=Z=e_{i}$ in (39), we get that

$$
\begin{align*}
a R\left(X, e_{i}\right) W & =[a+(n-1) b]\left[\eta(W) X-g(X, W) e_{i}\right] \\
& -b\left[S\left(e_{i}, W\right) X-S(X, W) e_{i}\right] \tag{40}
\end{align*}
$$

By taking the inner product of (40) with $W$ and on taking summation over $1 \leq i \leq n$ we get

$$
\begin{equation*}
S(X, W)=(n-1) g(X, W) \tag{41}
\end{equation*}
$$

This proves that the manifold is Einstein.
Finally, by taking $X=W=e_{i}$ in (41) and on taking summation from 1 to $n$ we obtain

$$
\begin{equation*}
r=n(n-1) \tag{42}
\end{equation*}
$$

Hence we can state that:

Theorem 4.1. If the pseudo-projective curvature tensor in an LP-Kenmotsu manifold is irrotational, then the manifold is Einstein and the scalar curvature under such conditions is given by $n(n-1)$.

## 5. Conservative pseudo-projective curvature tensor in $L P$-Kenmotsu manifolds

On differentiating (1) with respect to $U$, we get
$\left(\nabla_{U} \bar{W}\right)(X, Y) Z=a\left(\nabla_{U} R\right)(X, Y) Z+b\left[\left(\nabla_{U} S\right)(Y, Z) X-\left(\nabla_{U} S\right)(X, Z) Y\right]$

$$
\begin{equation*}
-\frac{d r(U)}{n}\left[\frac{a}{n-1}+b\right][g(Y, Z) X-g(X, Z) Y], \tag{43}
\end{equation*}
$$

which on contraction with respect to $U$ becomes
$(\operatorname{div} \bar{W})(X, Y) Z=a[(\operatorname{div} R)(X, Y) Z]+b\left[\left(\nabla_{X} S\right)(Y, Z)-\left(\nabla_{Y} S\right)(X, Z)\right]$

$$
\begin{equation*}
-\frac{1}{n(n-1)}[a+(n-1) b][g(Y, Z) d r(X)-g(X, Z) d r(Y)] \tag{44}
\end{equation*}
$$

for arbitrary vector fields $X, Y, Z, U \in \chi\left(M_{n}\right)$.
Let us suppose that the pseudo-projective curvature tensor is conservative, i. e., div $\bar{W}=0$. Then, (44) can be written as:

$$
\begin{align*}
& (a+b)\left[\left(\nabla_{X} S\right)(Y, Z)-\left(\nabla_{Y} S\right)(X, Z)\right] \\
& =\frac{1}{n(n-1)}[a+(n-1) b][g(Y, Z) d r(X)-g(X, Z) d r(Y)] \tag{45}
\end{align*}
$$

By putting $X=\xi$ in (45), we have

$$
\begin{align*}
& (a+b)\left[\left(\nabla_{\xi} S\right)(Y, Z)-\left(\nabla_{Y} S\right)(\xi, Z)\right] \\
& =\frac{1}{n(n-1)}[a+(n-1) b][g(Y, Z) d r(\xi)-g(\xi, Z) d r(Y)] . \tag{46}
\end{align*}
$$

On the other hand, since $\xi$ is a Killing vector and the scalar curvature $r$ remains invariant, we have $d r(\xi)=0$.

Also, we have

$$
\left(\nabla_{\xi} S\right)(Y, Z)=\xi S(Y, Z)-S\left(\nabla_{\xi} Y, Z\right)-S\left(Y, \nabla_{\xi} Z\right)
$$

and

$$
\left(\nabla_{Y} S\right)(\xi, Z)=\nabla_{Y} S(\xi, Z)-S\left(\nabla_{Y} \xi, Z\right)-S\left(\xi, \nabla_{Y} Z\right)
$$

for any vector fields $Y, Z \in \chi\left(M_{n}\right)$.
By virtue of the above, the relation (46) becomes

$$
\begin{align*}
& (a+b)\left[-\nabla_{Y}(S(\xi, Z))+S\left(\nabla_{Y} \xi, Z\right)+S\left(\xi, \nabla_{Y} Z\right)\right] \\
& =\frac{1}{n(n-1)}[a+(n-1) b][-\eta(Z) d r(Y)] \tag{47}
\end{align*}
$$

which on using (6) reduces to

$$
\begin{align*}
& (a+b)\left[-\nabla_{Y}\{(n-1) \eta(Z)\}+S\left(-\phi^{2} Y, Z\right)+(n-1) \eta\left(\nabla_{Y} Z\right)\right] \\
& =\frac{1}{n(n-1)}[a+(n-1) b][-\eta(Z) d r(Y)] \tag{48}
\end{align*}
$$

and further it is simplified to

$$
\begin{align*}
& (a+b)\left[-(n-1) \nabla_{Y}\{\eta(Z)\}-S(\phi Y, \phi Z)+(n-1) \eta\left(\nabla_{Y} Z\right)\right] \\
& =\frac{1}{n(n-1)}[a+(n-1) b][-\eta(Z) d r(Y)], \tag{49}
\end{align*}
$$

for arbitrary vector fields $Y, Z \in \chi\left(M_{n}\right)$.
By putting $Z=\phi Z$ in (49), we get

$$
\begin{equation*}
(a+b)\left[-S\left(\phi Y, \phi^{2} Z\right)+(n-1) \eta\left(\nabla_{Y}(\phi Z)\right)\right]=0 . \tag{50}
\end{equation*}
$$

If $a+b \neq 0$, then (50) becomes

$$
\begin{equation*}
S(\phi Y, Z)=(n-1) g(\phi Y, Z) \tag{51}
\end{equation*}
$$

By putting $Z=\phi Z$ in (51), we get

$$
\begin{equation*}
S(\phi Y, \phi Z)=(n-1) g(\phi Y, \phi Z) \tag{52}
\end{equation*}
$$

and this implies that

$$
\begin{equation*}
S(Y, Z)=(n-1) g(Y, Z), \tag{53}
\end{equation*}
$$

which on contracting gives

$$
\begin{equation*}
r=\sum_{i=1}^{3} \epsilon_{i} S\left(e_{i}, e_{i}\right) \text { and } \epsilon_{i}=g\left(e_{i}, e_{i}\right), \text { which is constant. } \tag{55}
\end{equation*}
$$

So, one can state that:
Theorem 5.1. An LP-Kenmotsu manifold admitting a conservative pseudoprojective curvature tensor is an Einstein manifold and it is of constant scalar curvature.

## 6. Example

Example 6.1. We consider a 3-dimensional manifold $M_{3}=\left\{(x, y, z) \in R^{3}\right\}$, where $(x, y, z)$ are the standard coordinates in $R^{3}$. Let $e_{1}, e_{2}$ and $e_{3}$ be the vector fields on $M_{3}$ given by

$$
\begin{equation*}
e_{1}=x \frac{\partial}{\partial x}=\xi, \quad e_{2}=x \frac{\partial}{\partial y}, \quad e_{3}=x \frac{\partial}{\partial z} . \tag{56}
\end{equation*}
$$

Clearly, $\left\{e_{1}, e_{2}, e_{3}\right\}$ is a set of linearly independent vectors for each point of $M_{3}$ and hence form a basis of $\chi\left(M_{3}\right)$.

The Lorentzian metric $g(X, Y)$ is defined by:

$$
g\left(e_{i}, e_{j}\right)= \begin{cases}-1, & \text { if } i=j=1 \\ 1, & \text { if } i=j=2 \text { or } 3 \\ 0, & \text { if } i \neq j ; i, j=1,2,3\end{cases}
$$

Let $\eta$ be the 1 -form defined by:

$$
\eta(Z)=g\left(Z, e_{1}\right), \text { for any } Z \in \chi\left(M_{3}\right) .
$$

Let $\phi$ be a (1, 1)-tensor field on $M_{3}$ defined by:

$$
\phi\left(e_{1}\right)=0, \phi\left(e_{2}\right)=-e_{2}, \phi\left(e_{3}\right)=-e_{3} \text { and } \phi^{2}\left(e_{1}\right)=0, \phi^{2}\left(e_{2}\right)=e_{2}, \phi^{2}\left(e_{3}\right)=e_{3} .
$$

The linearity of $\phi$ and $g(X, Y)$ yields that

$$
\eta\left(e_{1}\right)=-1, \phi^{2}(Z)=Z+\eta(Z) e_{1} \text { and } g(\phi X, \phi Y)=g(X, Y)+\eta(X) \eta(Y)
$$

for any vector fields $X, Y, Z \in \chi\left(M_{3}\right)$. Thus, for $e_{1}=\xi$, the structure $(\phi, \xi, \eta, g)$ defines a Lorentzian almost paracontact structure on $M_{3}$.

Let $\nabla$ be the Levi-Civita connection with respect to the Lorentzian metric $g$. Then, we have [14]

$$
\left[e_{1}, e_{2}\right]=e_{2},\left[e_{1}, e_{3}\right]=e_{3},\left[e_{2}, e_{3}\right]=0
$$

The Koszul's formula is defined by

$$
\begin{align*}
2 g\left(\nabla_{X} Y, Z\right) & =X g(Y, Z)+Y g(Z, X)-Z g(X, Y) \\
& -g(X,[Y, Z])-g(Y,[X, Z])+g(Z,[X, Y]) . \tag{57}
\end{align*}
$$

By using the above Koszul's formula and on taking $e_{1}=\xi$, we get the following [14]:

$$
\begin{align*}
\nabla_{e_{1}} e_{1} & =0, \nabla_{e_{1}} e_{2}=0, \nabla_{e_{1}} e_{3}=0, \\
\nabla_{e_{2}} e_{1} & =-e_{2}, \nabla_{e_{2}} e_{2}=-e_{1}, \nabla_{e_{2}} e_{3}=0,  \tag{58}\\
\nabla_{e_{3}} e_{1} & =-e_{3}, \nabla_{e_{3}} e_{2}=0, \nabla_{e_{3}} e_{3}=-e_{1} .
\end{align*}
$$

From the above calculations, we see that the manifold under consideration satisfies all the properties of Lorentzian para-Kenmotsu manifold i.e., $\nabla_{X} \xi=$ $-\phi^{2} X=-X-\eta(X) \xi$ and $\left(\nabla_{X} \phi\right) Y=-g(\phi X, Y) \xi-\eta(Y) \phi X$, for all $e_{1}=\xi$. Thus, the manifold $M_{3}$ under consideration with the structure $(\phi, \xi, \eta, g)$ is a 3 -dimensional Lorentzian para-Kenmotsu manifold [14].

It is known that

$$
\begin{equation*}
R(X, Y) Z=\nabla_{X} \nabla_{Y} Z-\nabla_{Y} \nabla_{X} Z-\nabla_{[X, Y]} Z \tag{59}
\end{equation*}
$$

Then, by using (58) and (59), the non-vanishing components of the curvature tensor are obtained as [14]:

$$
\begin{align*}
& R\left(e_{1}, e_{2}\right) e_{1}=e_{2}, R\left(e_{1}, e_{2}\right) e_{2}=e_{1}, R\left(e_{1}, e_{3}\right) e_{1}=e_{3}  \tag{60}\\
& R\left(e_{1}, e_{3}\right) e_{3}=e_{1}, R\left(e_{2}, e_{3}\right) e_{2}=-e_{3}, R\left(e_{2}, e_{3}\right) e_{3}=e_{2}
\end{align*}
$$

With the help of above expressions of the curvature tensors, it follows that

$$
\begin{equation*}
R(X, Y) Z=g(Y, Z) X-g(X, Z) Y \tag{61}
\end{equation*}
$$

This proves that the 3 -dimensional manifold $M_{3}$ under consideration is an $L P$ Kenmotsu manifold and it admits a pseudo-projective curvature tensor.

Let $X, Y$ and $Z$ be any three vector fields given by:

$$
\begin{equation*}
X=a_{1} e_{1}+a_{2} e_{2}+a_{3} e_{3}, Y=b_{1} e_{1}+b_{2} e_{2}+b_{3} e_{3}, Z=c_{1} e_{1}+c_{2} e_{2}+c_{3} e_{3} \tag{62}
\end{equation*}
$$

where $a_{i}, b_{i}, c_{i}$ are all non-zero real numbers, for all $i=1,2,3$.
By putting $Z=\xi=e_{1}$ in (61) and on using (62), we get that

$$
R(X, Y) \xi=\eta(Y) X-\eta(X) Y=a_{1} b_{2} e_{2}+a_{1} b_{3} e_{3}-a_{2} b_{1} e_{2}-a_{3} b_{1} e_{3}
$$

Further, in view of (61) and (62), we get

$$
\begin{aligned}
R(X, Y) Z & =g(Y, Z) X-g(X, Z) Y=\left(c_{1} e_{2}+c_{2} e_{1}\right)\left(a_{1} b_{2}-a_{2} b_{1}\right) \\
& +\left(a_{1} b_{3}-a_{3} b_{1}\right)\left(c_{1} e_{3}+c_{3} e_{1}\right)+\left(a_{2} b_{3}-a_{3} b_{2}\right)\left(c_{3} e_{2}-c_{2} e_{3}\right)
\end{aligned}
$$

and hence from (1) we have

$$
\begin{align*}
\bar{W}(X, Y) Z & =[a+(n-1) b]\left[1-\frac{r}{n(n-1)}\right]\left(c_{1} e_{2}+c_{2} e_{1}\right)\left(a_{1} b_{2}-a_{2} b_{1}\right)  \tag{63}\\
& +\left(a_{1} b_{3}-a_{3} b_{1}\right)\left(c_{1} e_{3}+c_{3} e_{1}\right)+\left(a_{2} b_{3}-a_{3} b_{2}\right)\left(c_{3} e_{2}-c_{2} e_{3}\right)
\end{align*}
$$

and

$$
\begin{align*}
& \bar{W}(X, Y) \xi \\
& =[a+(n-1) b]\left[1-\frac{r}{n(n-1)}\right]\left(a_{1} b_{2} e_{2}+a_{1} b_{3} e_{3}-a_{2} b_{1} e_{2}-a_{3} b_{1} e_{3}\right) . \tag{64}
\end{align*}
$$

Hence, we can say that $\bar{W}(X, Y) Z=0$ (or) $\bar{W}(X, Y) \xi=0$, only if $\frac{a_{1}}{b_{1}}=\frac{a_{2}}{b_{2}}=\frac{a_{3}}{b_{3}}$.
This proves that the manifold $M_{3}$ under consideration is an $L P$-Kenmotsu manifold and it admits a flat pseudo-projective curvature tensor, provided the above condition is satisfied.

Further, by using (60), we obtain the Ricci tensors and scalar curvatures as follows: $S\left(e_{1}, e_{1}\right)=-2, S\left(e_{2}, e_{2}\right)=2, S\left(e_{3}, e_{3}\right)=2$ and $r=6$, where

$$
\begin{gathered}
S(X, Y)=\sum_{i=1}^{3} \epsilon_{i} g\left(R\left(e_{i}, X\right) Y, e_{i}\right) \\
r=\sum_{i=1}^{3} \epsilon_{i} S\left(e_{i}, e_{i}\right) \text { and } \epsilon_{i}=g\left(e_{i}, e_{i}\right)
\end{gathered}
$$

The above arguments verifies the results discussed in sections 4 and 5 .

## 7. Conclusions

The present work explores the geometrical significance of a new class of Lorentzian paracontact metric manifolds namely Lorentzian para-Kenmotsu manifolds whenever a pseudo-projective curvature tensor admitted by these manifolds exhibits the physical phenomena, i.e., the curvature tensor is either irrotational or conservative.

## 8. Acknowledgements

The authors acknowledge Dr. A. Kameswara Rao, Assistant Professor of G. V. P. College of Engineering for Women for his valuable suggestions in preparation of the manuscript. The authors also heartily thank all the reviewers for their valuable suggestions on the paper.

## References

[1] Abdul Haseeb and Rajendra Prasad, Certain results on Lorentzian para-Kenmotsu manifolds, Bulletin of Parana's Mathematical Society, doi.10.5269/bspm.40607, 2018.
[2] C. S. Bagewadi, E. Girish Kumar, Venkatesha, On irrotational pseudo projective curvature tensor, Novisad Jou. Math., 35 (2005), 85-92.
[3] C. S. Bagewadi, Venkatesha, Some curvature conditions on a Kenmotsu manifolds, Proc. Nat. Con., (2004), 85-92.
[4] C. S. Bagewadi, Venkatesha, Some curvature conditions on a Kenmotsu manifolds, Tensor N. S., 68 (2007), 140-147.
[5] C. S. Bagewadi, Venkatesha, N. S. Basavarajappa, On LP-Sasakian manifolds, Scientia, Series A: Mathematical Sciences, 16 (2008), 1-8.
[6] Bhagawat Prasad, A pseudo projective curvature tensor on a Riemannian manifolds, Bull. Cal. Math. Soc., 94 (2002), 163-166.
[7] U. C. De, K. Matsumoto, A. A. Shaikh, On Lorentzian para-Sasakian manifolds, Rendiconti del Seminario Matematico di Messina, Serie II, Supplemento al n. 3, (1999), 149-158.
[8] K. Matsumoto, On Lorentzian paracontact manifolds, Bulletin of the Yamagata University Natural Science, 12 (1989), 151-156.
[9] K. Matsumoto, I. Mihai, On a certain transformation in a Lorentzian paraSasakian manifold, Tensor, N.S., 47 (1988), 189-197.
[10] I. Mihai, R. Rosca, On Lorentzian p-Sasakian manifolds, Classical Analysis, World Scientific Publ., Singapore, (1992), 155-169.
[11] I. Mihai, A. A. Shaikh, U. C. De, On Lorentzian para-Sasakian manifolds, Rendiconti del Seminario Matematico di Messina, Serie II, (1999).
[12] G. P. Pokhariyal, R. S. Mishra, The curvature tensors and their relativistic significance, Yokohoma Math. J., 18 (1970), 105-108.
[13] Rajendra Prasad, Abdul Haseeb, Umesh Kumar Gautam, On $\check{\phi}$ semisymmetric LP-Kenmotsu manifolds with a QSNM-connection admitting Ricci solitons, Kragujevac Journal of Mathematics, 45 (2021), 815-827.
[14] K. L. Sai Prasad, S. Sunitha Devi, G. V. S. R. Deekshitulu, On a class of Lorentzian para-Kenmotsu manifolds admitting the Weyl-projective curvature tensor of type (1,3), Italian Journal of Pure and Applied Mathematics, 45 (2021), 990-1001.
[15] B. B. Sinha, K. L. Sai Prasad, A class of almost para contact metric manifold, Bulletin of the Calcutta Mathematical Society, 87(1995), 307-312.
[16] Venkatesha, C. S. Bagewadi, On concircular $\phi$-recurrent LP-Sasakian manifolds, Differ. Geom. Dyn. Syst., 10 (2008), 312-319.
[17] Venkatesha, C. S. Bagewadi, K. T. Pradeep Kumar, Some results on Lorentzian para-Sasakian manifolds, ISRN Geometry, Vol. 2011, Article ID 161523, 9 pages, 2011.

Accepted: September 20, 2021

