## A note on $b$-generalized derivations in rings with involution

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#### Abstract

Let $R$ be a ring with involution $*$. The purpose of this paper is to investigate the special type of mappings defined on $(R, *)$. In fact it is shown that these mappings are actually the $b$-generalized derivation defined on $R$.


Keywords: prime ring, derivation, b-generalized derivation, involution.
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## 1. Introduction

Throughout this article, $R$ be a prime ring with involution and $Q_{r}$ will be the right Martindale quotient ring of $R$. For any $x, y \in R$, the symbol $[x, y]$ will denote the commutator $x y-y x$, while the symbol $x \circ y$ will stand for the anticommutator $x y+y x . R$ is said to be 2 -torsion free if whenever $2 x=0$; with $x \in R$ implies $x=0 . R$ is prime if $x R y=(0)$, where $x, y \in R$, implies $x=0$ or $y=0$ and is called a semiprime ring in case $x R x=(0)$ implies $x=0$. A derivation on $R$ is an additive mapping $d: R \rightarrow R$ such that $d(x y)=d(x) y+x d(y)$, for all $x, y \in R$. A derivation $d$ is said to be inner if there exists $a \in R$ such that $d(x)=a x-x a$, for all $x \in R$. Following Brešar [9], an additive mapping $F: R \rightarrow R$ is called a generalized derivation if there exists a derivation $d: R \rightarrow R$ such that $F(x y)=F(x) y+x d(y)$, for all $x, y \in R$. Basic examples are derivations and generalized inner derivations are maps of type $x \mapsto a x+x b$ for some $a, b \in R$.

Many results in the literature indicate how the global structure of a ring $R$ is often tightly connected to the behavior of additive mappings defined on $R$. Many results in this direction can be found in $[1,5,6,7,8,9,10,15,16,17]$. Very recently Koşan and Lee [14] introduced the new concept of left $b$-generalized derivation as follows: Let $d: R \rightarrow Q_{r}$ be an additive mapping and $b \in Q_{r}$. An additive mapping $F: R \rightarrow Q_{r}$ is called a left $b$-generalized derivation, with an associated mapping $d$, if $F(x y)=F(x) y+b x d(y)$, for all $x, y \in R$. Moreover, it is prove that if $R$ is a prime ring, then $d$ is a derivation of R. In the present paper, this mapping $F$ will be called a $b$-generalized derivation with an associated derivation $d$. It is easy to see that every generalized derivation is a 1 generalized derivation. For instance for any $x \in R$, the mapping $x: \rightarrow a x+b x c$ for $a, b, c \in Q$ is a $b$-generalized derivation of $R$, which is known as inner $b$ generalized derivation of $R$.

An additive mapping $*: R \rightarrow R$ is called an involution if $*$ is an antiautomorphism of order 2 , that is $\left(x^{*}\right)^{*}=x$, for all $x \in R$. A ring equipped with an involution $*$ is called an involution ring. Very recently, many authors have studied certain additive mappings like derivations, generalized derivations in the setting of rings with involution (see [2, 3, 4, 11, 12] for references). They not only characterized these mappings but also found that there is a close connection between the commutativity of $R$ and these mappings. Here our emphasis will be more in the direction of the a special type of mapping defined on $R$, which were first studied in [18].

In fact, our motivations comes from [ [13], Theorem 4.1.2], which stated as: Let $R$ be a simple ring with involution of characteristic not 2 , such that $\operatorname{dim}_{Z} R>4$. Let $d: R \rightarrow R$ be such that $d\left(x x^{*}\right)=d(x) x^{*}+x d\left(x^{*}\right)$, for all $x \in R$. Then $d$ is a derivation of $R$. We prove the following results.

Theorem 1.1. Let $R$ be a 2 -torsion free semiprime $*$-ring with involution such that $R$ has a commutator which is not a zero divisor. If there exists an additive mapping $F: R \rightarrow R$ associated with a nonzero derivation $d: R \rightarrow R$ such that
$F\left(x x^{*}\right)=F(x) x^{*}+b x d\left(x^{*}\right)$, for all $x \in R$, where $b$ is a fixed element of $R$. Then $F$ is a b-generalized derivation.

Theorem 1.2. Let $R$ be a 2-torsion free semiprime $*-$ ring and let $R$ has a commutator which is not a zero divisor. If there exists an additive mapping $F: R \rightarrow R$ associated with a nonzero derivation $d: R \rightarrow R$ such that $F\left(x y^{*} x\right)=$ $F(x) y^{*} x+b x d\left(y^{*}\right) x+b x y^{*} d(x)$, for all $x, y \in R$ and $b$ is a fixed element of $R$. Then $F$ is a b-generalized derivation.

## 2. Main results

To prove the above results we need the following lemma.
Lemma 2.1. Let $R$ be a 2-torsion free ring and let $F: R \rightarrow R$ be an additive mapping associated with a nonzero derivation $d: R \rightarrow R$ such that $F\left(x^{2}\right)=$ $F(x) x+b x d(x)$, where $b$ is a fixed element of $R$. Then, for all $x, y, z \in R$, the following statements hold:
(i) $F(x y+y x)=F(x) y+F(y) x+b x d(y)+b y d(x)$;
(ii) $F(x y x)=F(x) y x+b x d(y) x+b x y d(x)$;
(iii) $F(x y z+z y x)=F(x) y z+F(z) y x+b x d(y) z+b x y d(z)+b z d(y) x+b z y d(x)$;
(iv) $\delta(x, y)[x, y]=0$, where $\delta(x, y)=F(x y)-F(x) y-b x d(y)$.

Proof. (i) We have

$$
\begin{equation*}
F\left(x^{2}\right)=F(x) x+b x d(x), \text { for all } x \in R . \tag{1}
\end{equation*}
$$

Replacing $x$ by $x+y$ and using (1), we get

$$
\begin{equation*}
F(x y+y x)=F(x) y+F(y) x+b x d(y)+b y d(x), \text { for all } x, y \in R . \tag{2}
\end{equation*}
$$

(ii) Taking $y=x y+y x$ in (2) and using it, we arrive at

$$
\begin{align*}
F\left(x^{2} y+y x^{2}\right)+2 F(x y x) & =F(x) x y+F(x) y x+F(x) y x \\
& +F(y) x^{2}+b x d(y) x+b y d(x) x \\
& +b x d(x) y+b x^{2} d(y)+b x d(y) x+b x y(x)  \tag{3}\\
& +b x y d(x)+b y x d(x), \text { for all } x, y \in R .
\end{align*}
$$

Replacing $x$ by $x^{2}$ in (2) and using (3) and the fact that $R$ is 2 -torsion free, we obtain

$$
\begin{equation*}
F(x y x)=F(x) y x+b x d(y) x+b x y d(x), \text { for all } x, y \in R . \tag{4}
\end{equation*}
$$

There by proving (ii).
(iii) Replacing $x$ by $x+z$ in (4) and using (4), we get
(5) $F(x y z+z y x)=F(x) y z+F(z) y x+b x d(y) z+b z d(y) x+b x y d(z)+b z y d(x)$,
for all $x, y \in R$. Thus proves (iii).
(iv) On substituting $x y-y x$ in place of $z$ in (5), we get $\delta(x, y)[x, y]=0$, for all $x, y \in R$, where $\delta(x, y)=F(x y)-F(x) y-b x d(y)$. This completes the proof of Lemma.

Proof of Theorem 1.1. We have

$$
\begin{equation*}
F\left(x x^{*}\right)=F(x) x^{*}+b x d\left(x^{*}\right), \text { for all } x \in R . \tag{6}
\end{equation*}
$$

On linearizing (6), we get
(7) $F\left(x y^{*}+y x^{*}\right)=F(x) y^{*}+F(y) x^{*}+b y d\left(x^{*}\right)+b x d\left(y^{*}\right)$, for all $x, y \in R$.

Taking $y=x^{*}$ in (7), we have

$$
F\left(x^{2}+\left(x^{*}\right)^{2}\right)+F(x) x+F\left(x^{*}\right) x^{*}+b x^{*} d\left(x^{*}\right)+b x d(x), \text { for all } x \in R .
$$

This can be further written as

$$
\begin{equation*}
B(x)+B\left(x^{*}\right)=0, \text { for all } x \in R, \tag{8}
\end{equation*}
$$

where $B(x)=F\left(x^{2}\right)-F(x) x-b x d(x)$, for all $x \in R$. Replacing $y$ by $x y^{*}+y x^{*}$ in (7), we obtain
$F\left(x\left(y+y^{*}\right) x^{*}\right)=-B(x) y^{*}+F(x)\left(y+y^{*}\right) x^{*}+b x d\left(y+y^{*}\right) x^{*}$, for all $x, y \in R$.
Using $y-y^{*}$ for $y$, we get

$$
\begin{equation*}
B(x) y=B(x) y^{*}, \text { for all } x, y \in R \tag{9}
\end{equation*}
$$

In view of [[19], Lemma 1], we get $B(x) \in Z(R)$, for all $x \in R$. Taking $y=y^{*}$ in (7), we arrive at
(10) $F\left(x y+y^{*} x^{*}\right)=F(x) y+F\left(y^{*}\right) x^{*}+b y^{*} d\left(x^{*}\right)+b x d(y)$, for all $x, y \in R$.

Replacing $y$ by $x y$ in (10), we get

$$
\begin{equation*}
F\left(x^{2} y+y^{*}\left(x^{*}\right)^{2}\right)=F(x) x y+F\left(y^{*} x^{*}\right) x^{*}+b x d(x) y+b x^{2} d(y)+b y^{*} x^{*} d\left(x^{*}\right) \tag{11}
\end{equation*}
$$

for all $x, y \in R$. Taking $x=x^{2}$ in (10), we obtain

$$
\begin{equation*}
F\left(x^{2} y+y^{*}\left(x^{*}\right)^{2}\right)=F\left(x^{2}\right) y+F\left(y^{*}\right)\left(x^{*}\right)^{2}+b x^{2} d(y)+b y^{*} d\left(\left(x^{*}\right)^{2}\right) \tag{12}
\end{equation*}
$$

for all $x, y \in R$. Using (11) and (12), we get
$\left(F\left(x^{2}\right)-F(x) x-b x d(x)\right) y+\left(F(y) x^{*}-F\left(y^{*} x^{*}\right)+b y^{*} d\left(x^{*}\right)\right) x^{*}=0$, for all $x, y \in R$.

Replacing $y$ by $x$, we have
$\left(F\left(x^{2}\right)-F(x) x-b x d(x)\right) x-\left(F\left(\left(x^{*}\right)^{2}-F\left(x^{*}\right) x^{*}-b x^{*} d\left(x^{*}\right)\right) x^{*}=0\right.$, for all $x \in R$.
This implies that

$$
B(x) x-B\left(x^{*}\right) x^{*}=0, \text { for all } x \in R .
$$

By (8), we arrive at

$$
\begin{equation*}
B(x)\left(x+x^{*}\right)=0, \text { for all } x \in R . \tag{13}
\end{equation*}
$$

Taking $y=x$ in (9), we get

$$
\begin{equation*}
B(x)\left(x-x^{*}\right)=0, \text { for all } x \in R . \tag{14}
\end{equation*}
$$

Thus in view of (13) and (14), we get $2 B(x) x=0$, for all $x \in R$. Since $R$ is 2 -torsion free, we obtain

$$
\begin{equation*}
B(x) x=0, \text { for all } x \in R . \tag{15}
\end{equation*}
$$

Since $B(x)$ is in $Z(R)$, this implies that $x B(x)=0$, for all $x \in R$. Linearizing (15), we get

$$
\begin{equation*}
B(x) y+B(y) x+\sigma(x, y) x+\sigma(x, y) y=0, \text { for all } x, y \in R \tag{16}
\end{equation*}
$$

where $\sigma(x, y)=F(x y+y x)-F(x) y-F(y) x-b x d(y)-b y d(x)$, for all $x, y \in R$. Taking $x=-x$ in (16), we have

$$
\begin{equation*}
B(x) y-B(y) x+\sigma(x, y) x-\sigma(x, y) y=0, \text { for all } x, y \in R \tag{17}
\end{equation*}
$$

Using (16) and (17), we arrive at $B(x) y+\sigma(x, y) x=0$, for all $x, y \in R$. Right multiplying by $B(x)$, we get $B(x) y B(x)+\sigma(x, y) x B(x)=0$, for all $x, y \in R$. This implies that $B(x) y B(x)=0$, for all $x, y \in R$. Since $R$ is a semiprime ring, we obtain $B(x)=0$, for all $x \in R$. This implies that

$$
\begin{equation*}
F\left(x^{2}\right)=F(x) x+b x d(x), \text { for all } x \in R . \tag{18}
\end{equation*}
$$

Let $u, v$ be fixed element of $R$ such that $w[u, v]=0$ or $[u, v] w=0$. Then in view of Lemma 2.1 (iv) and hypothesis

$$
\begin{equation*}
\delta(u, v)=0, \tag{19}
\end{equation*}
$$

we have to show that $\delta(x, y)=0$, for all $x, y \in R$. Again in view of Lemma 2.1 (iv), we have

$$
\begin{equation*}
\delta(x, y)[x, y]=0 . \tag{20}
\end{equation*}
$$

Replacing $x$ by $x+u$ and using (20), we get

$$
\begin{equation*}
\delta(x, y)[u, y]+\delta(u, y)[x, y]=0, \quad \text { for all } x, y \in R . \tag{21}
\end{equation*}
$$

On substituting $y$ by $y+v$ and using (19) and (20), we have
(22) $\delta(x, y)[u, v]+\delta(x, v)[u, y]+\delta(x, v)[u, v]+\delta(u, y)[x, v]=0$, for all $x, y \in R$.

Taking $x=u$ in (22) and making use of (19), we obtain $2 \delta(u, y)[u, v]=0$, for all $y \in R$. Since $R$ is 2 -torsion free and using the given assumption, we have

$$
\begin{equation*}
\delta(u, y)=0, \text { for all } y \in R . \tag{23}
\end{equation*}
$$

Again replacing $y$ by $v$ in (21) and using (19), we get $\delta(x, v)[u, v]=0$, for all $x, y \in R$. Since $[u, v]$ is not a zero divisor, we get

$$
\begin{equation*}
\delta(x, v)=0, \text { for all } x \in R . \tag{24}
\end{equation*}
$$

Thus by (22), (23) and (24) we get $\delta(x, y)[u, v]=0$, for all $x, y \in R$. This implies that $\delta(x, y)=0$, for all $x, y \in R$ i.e., $F(x y)=F(x) y+b x d(y)$, for all $x, y \in R$, which completes the proof.

Proof of Theorem 1.2. By the given hypothesis, we have

$$
\begin{equation*}
F\left(x y^{*} x\right)=F(x) y^{*} x+b x d\left(y^{*}\right) x+b x y^{*} d(x), \text { for all } x, y \in R . \tag{25}
\end{equation*}
$$

On substituting $x$ by $x+z$ and on solving, we have

$$
\begin{align*}
F\left(x y^{*} z+z y^{*} x\right) & =F(x) y^{*} z+F(z) y^{*} x+b x d\left(y^{*}\right) z \\
& +b z d\left(y^{*}\right) x+b x y^{*} d(z)+b z y^{*} d(x) \tag{26}
\end{align*}
$$

for all $x, y, z \in R$. Replacing $z$ by $x^{2}$ in (26), we get

$$
\begin{align*}
F\left(x y^{*} x^{2}+x^{2} y^{*} x\right) & =F(x) y^{*} x^{2}+F\left(x^{2}\right) y^{*} x+b x d\left(y^{*}\right) x^{2}+b x^{2} d\left(y^{*}\right) x \\
& +b x y^{*} d(x) x+b x y^{*} x d(x)+b x^{2} y^{*} d(x), \text { for all } x, y \in R . \tag{27}
\end{align*}
$$

Taking $y$ as $x^{*} y+y x^{*}$ in (25), we obtain

$$
\begin{align*}
F\left(x y^{*} x^{2}+x^{2} y^{*} x\right) & =F(x) y^{*} x^{2}+F(x) x y^{*} x+b x d\left(y^{*}\right) x^{2} \\
& +b x y^{*} d(x) x+b x d(x) y^{*} x  \tag{28}\\
& +b x^{2} d\left(y^{*}\right) x+b x y^{*} x d(x)+b x^{2} y^{*} d(x), \text { for all } x, y \in R .
\end{align*}
$$

On comparing (27) and (28), we arrive at

$$
\begin{equation*}
\left(F\left(x^{2}\right)-F(x) x-b x d(x)\right) y^{*} x=0, \text { for all } x, y \in R . \tag{29}
\end{equation*}
$$

This can be further written as

$$
\begin{equation*}
\phi(x) y^{*} x=0, \text { for all } x, y \in R \tag{30}
\end{equation*}
$$

where $\phi(x)=F\left(x^{2}\right)-F(x) x-b x d(x)$. Replacing $y$ by $y^{*} x^{*}$ in (30), we get $\phi(x) x y x=0$. Now replacing $y$ by $z \phi(x)$, we get $\phi(x) x z \phi(x) x=0$, for all $x, z \in R$. Using the semiprimeness of $R$, we obtain

$$
\begin{equation*}
\phi(x) x=0, \text { for all } x \in R . \tag{31}
\end{equation*}
$$

Taking $x=x+y$, we get

$$
\begin{equation*}
\phi(x) y+\beta(x, y) x+\phi(y) x+\beta(x, y) y=0, \text { for all } x, y \in R, \tag{32}
\end{equation*}
$$

where $\beta(x, y)=F(x y+y x)-F(x) y-F(y) x-b x d(y)-b y d(x)$. Replacing $x$ by $-x$ in (32) and making use of (32), we get

$$
2(\phi(x) y+\beta(x, y) x)=0, \text { for all } x, y \in R
$$

Since $R$ is 2-torsion free, we arrive at

$$
\begin{equation*}
\phi(x) y+\beta(x, y)=0, \text { for all } x, y \in R . \tag{33}
\end{equation*}
$$

Multiplying (33) by $\phi(x)$ on the right side, we get

$$
\begin{equation*}
\phi(x) y \phi(x)+\beta(x, y) x \phi(x)=0, \text { for all } x, y \in R . \tag{34}
\end{equation*}
$$

Taking $y=y^{*}$ in (30), we get $\phi(x) y x=0$, for all $x, y \in R$. This further implies that $x \phi(x) y x \phi(x)=0$, for all $x, y \in R$. Thus by the semiprimeness of $R$, we get $x \phi(x)=0$, for all $x \in R$. Using this in (34), we obtain $\phi(x)=0$, for all $x \in R$. Hence $F\left(x^{2}\right)=F(x) x+b x d(x)$, for all $x \in R$. Now, following on similar lines as after (18), we get the required result.

## Acknowledgements

The authors wish to express their sincere thanks to Professor P. Corsini, Professor I. Cristea and the anonymous referees for their valuable comments, suggestions and advice to improve the article in the present shape.

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Accepted: December 27, 2021

