

## A note on Einstein-like $\epsilon$ -LP-Sasakian manifolds

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**Abstract.** The present paper deals with the study on Einstein-like  $\epsilon$ -Lorentzian para-Sasakian manifolds. A necessary and sufficient condition for an  $\epsilon$ -Lorentzian para-Sasakian manifold to be Einstein-like is obtained in terms of its curvature tensor. We also obtain the scalar curvature of an Einstein-like  $\epsilon$ -Lorentzian para-Sasakian manifold. A necessary and sufficient condition for an  $\epsilon$ -Lorentzian almost para-contact metric hypersurface of an indefinite locally Riemannian product manifold to be  $\epsilon$ -Lorentzian para-Sasakian is derived as well as it is shown that the  $\epsilon$ -Lorentzian para-Sasakian hypersurface of an indefinite locally Riemannian product manifold of almost constant curvature is always Einstein-like.

**Keywords:**  $\epsilon$ -LP-Sasakian manifold, Einstein-like manifold,  $\epsilon$ -LP-Sasakian hypersurfaces.

### 1. Introduction

Semi-Riemannian geometry has great importance in the field of general relativity [8] and different areas of physics. I. Sato [11] introduced a structure  $(\phi, \xi, \eta)$  satisfying  $\phi^2 = I - \eta \otimes \xi$  and  $\eta(\xi) = 1$  on a differentiable manifold in 1976, which is now renowned as an almost para-contact structure. This structure is an analogue of the almost contact structure [5, 10] as well as closely related to the almost product structure. Almost contact manifold is always odd dimen-

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sional but almost para-contact manifold could be even-dimensional as well. T. Adati and K. Motsumoto [1] defined and studied  $p$ -Sasakian manifold and special  $p$ -Sasakian manifolds in 1977, which are considered as a special kind of an almost contact Riemannian manifold. Further in 1989, Matsumoto [7] used the structure vector field  $-\xi$  instead of  $\xi$  in an almost para-contact manifold and associated a Lorentzian metric with the resulting structure, called it a Lorentzian almost para-contact manifold. Such structures are also studied by several authors ([2], [4], [13]). The concept of  $\epsilon$ -Sasakian manifold is introduced by A. Bejancu and K. L. Duggal in 1993 [3]. M. M. Tripathi, Kilic, Perktas and Keles have studied  $\epsilon$ -almost para-contact manifolds and in particular,  $\epsilon$ -para-Sasakian manifolds. U. C. De and A. Sarkar [6] introduced  $\epsilon$ -Kenmotsu manifold in 2009 and studied some curvature properties on the manifold. R. Prasad and V. Srivastava [9] have studied  $\epsilon$ -Lorentzian para-Sasakian manifold and also shown its existence by an example in 2012. In 2017, Haseeb, Prakash and Siddiqi [14] have studied quarter-symmetric metric connection in an  $\epsilon$ -Lorentzian para-Sasakian manifolds.

R. Sharma [12] introduced and studied Einstein-like para-Sasakian manifolds in 1982. Motivated by his study, in this paper we introduce and study Einstein-like  $\epsilon - LP$ -Sasakian manifold. The paper is organized as follows: In section 2, we give some preliminaries about  $\epsilon - LP$ -Sasakian manifolds. Section 3 contains definition of an Einstein-like para-Sasakian manifold and some basic properties. We also find some results on scalar curvature and a necessary and sufficient condition for  $\epsilon - LP$ -Sasakian manifolds to be Einstein-like in terms of its curvature tensor is obtain. In section 4, we obtain a necessary and sufficient condition for  $\epsilon$ -Lorentzian almost para-contact metric hypersurface of an indefinite locally Riemannian product manifold to be  $\epsilon - LP$ -Sasakian manifold. Finally, we prove that  $\epsilon - LP$ -Sasakian hypersurface of an indefinite locally Riemannian product manifold of almost constant curvature is always Einstein-like.

## 2. Preliminaries

A structure on a differential manifold  $M$  of dimension  $n$  is called an  $\epsilon$ -Lorentzian almost para-contact metric structure if it admits a  $(1, 1)$ -tensor field  $\phi$ , a contravariant vector field  $\xi$ , a 1-form  $\eta$  and semi-Riemannian metric  $g$  which satisfy

- (1)  $\phi^2 X = X + \eta(X)\xi, \quad \eta(\xi) = -1,$
- (2)  $g(X, \xi) = \epsilon\eta(X) \Rightarrow g(\xi, \xi) = -\epsilon,$
- (3)  $\phi(\xi) = 0, \quad \eta(\phi X) = 0,$
- (4)  $g(\phi X, \phi Y) = g(X, Y) + \epsilon\eta(X)\eta(Y),$

for all vector fields  $X, Y \in \chi(M)$ , where  $\epsilon$  is 1 or  $-1$  according to the vector field  $\xi$  being timelike or spacelike.

If an  $\epsilon$ -Lorentzian almost para-contact metric structure satisfies

$$(5) \quad (\nabla_X \phi)Y = g(X, Y)\xi + \epsilon\eta(Y)X + 2\epsilon\eta(X)\eta(Y)\xi,$$

where  $\nabla$  denotes the Levi-Civita connection with respect to  $g$ , then  $M$  is called an  $\epsilon$ -LP-Sasakian manifold.

In an  $\epsilon$ -LP-Sasakian manifold, we have [9]

$$(6) \quad \nabla_X \xi = \epsilon \phi X,$$

$$(7) \quad (\nabla_X \eta)Y = g(\phi X, Y) = \Phi(X, Y).$$

Moreover, the curvature tensor  $R$  and Ricci tensor  $S$  satisfy the following equations:

$$(8) \quad R(X, Y)\xi = \eta(Y)X - \eta(X)Y,$$

$$(9) \quad S(X, \xi) = (n - 1)\eta(X).$$

**Example 2.1.** Let a 3-dimensional manifold  $M_3 = \{(x, y, z) \in R^3\}$ , where  $(x, y, z)$  are standard coordinates of  $R^3$ . Let  $e_1, e_2$  and  $e_3$  be vector fields on  $M_3$  given by

$$e_1 = \frac{1}{2}e^{2z} \frac{\partial}{\partial y}, \quad e_2 = \frac{1}{2}e^{2z} \left( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right) \text{ and } e_3 = \frac{\partial}{\partial z} = \xi,$$

which are linearly independent vector fields at each point of  $M_3$  and form a basis of  $T_p M_3$  at each point  $p$  of  $M_3$ . Define a semi-Riemannian metric  $g$  on  $M_3$  as  $g(e_i, e_i) = 1$ , for  $1 \leq i \leq 2$ ,  $g(e_3, e_3) = -\epsilon$  and  $g(e_i, e_j) = 0$ , for  $i \neq j$  and  $1 \leq i, j \leq 3$ .

Let  $\eta$  be a 1-form on  $M_3$  defined as  $\epsilon\eta(U) = g(U, e_3) = g(U, \xi)$ , for all  $U \in \chi(M_3)$  and let  $\phi$  be a  $(1, 1)$  tensor field on  $M_3$  defined as

$$\phi(e_1) = -\epsilon e_1, \quad \phi(e_2) = -\epsilon e_2, \quad \phi(e_3) = 0.$$

By applying linearity of  $\phi$  and  $g$ , we have

$$\eta(\xi) = -1, \quad \phi^2(X) = X + \eta(X)\xi,$$

and

$$g(\phi X, \phi Y) = g(X, Y) + \epsilon\eta(X)\eta(Y) \quad \text{for all } X, Y \in \chi(M_3).$$

Let  $\nabla$  be a Levi-Civita connection with respect to the semi-Riemannian metric  $g$ . Then we have

$$[e_1, e_2] = 0, \quad [e_2, e_3] = -e_2, \quad [e_1, e_3] = -e_1,$$

The Riemannian connection  $\nabla$  of the metric  $g$  is given by

$$2g(\nabla_U V, W) = Ug(V, W) + Vg(W, U) - Wg(U, V) \\ - g(U, [V, W]) - g(V, [U, W]) + g(W, [U, V]),$$

which is known as Koszul’s formula, we can easily calculate

$$\begin{aligned} \nabla_{e_1} e_1 &= -\epsilon e_3, & \nabla_{e_1} e_2 &= 0, & \nabla_{e_1} e_3 &= -e_1, \\ \nabla_{e_2} e_1 &= 0, & \nabla_{e_2} e_2 &= -\epsilon e_3, & \nabla_{e_2} e_3 &= -e_2, \\ \nabla_{e_3} e_1 &= 0, & \nabla_{e_3} e_2 &= 0, & \nabla_{e_3} e_3 &= 0. \end{aligned}$$

From the above it follows that the manifold satisfies  $\nabla_X \xi = \epsilon \phi X$ , for  $\xi = e_3$  and  $(\nabla_X \phi)Y = g(X, Y)\xi + \epsilon \eta(Y)X + 2\epsilon \eta(X)\eta(Y)\xi$ . Hence the manifold is an  $\epsilon$ -LP-Sasakian manifold.

**3. Einstein-like  $\epsilon$ -LP-Sasakian manifolds**

We begin with the following definition analogous to Einstein-like para-Sasakian manifolds (Sharma, 1982).

**Definition 3.1.** *An  $\epsilon$ -Lorentzian almost para contact metric manifold is said to be Einstein-like if its Ricci tensor  $S$  satisfies*

$$(10) \quad S(X, Y) = ag(X, Y) + b\eta(X)\eta(Y) + cg(\phi X, Y),$$

for some real constants  $a, b$  and  $c$ .

**Proposition 3.1.** *In an Einstein-like  $\epsilon$ -Lorentzian almost para contact metric manifold, we have*

$$(11) \quad S(\phi X, Y) = ag(\phi X, Y) + cg(\phi X, \phi Y),$$

$$(12) \quad S(X, \xi) = \epsilon a\eta(X) - b\eta(X).$$

Moreover, if the manifold is  $\epsilon$ -LP-Sasakian manifold, the following conditions also hold

$$(13) \quad \epsilon a - b = n - 1,$$

$$(14) \quad r = na - \epsilon b + c(\text{trace}(\phi)).$$

**Proof.** The equations (11) and (12) are obvious from (10).

In an  $\epsilon$ -LP-Sasakian manifold, it follows that  $S(X, \xi) = (n - 1)\eta(X)$ , which in view of (12) implies (13).

Now, let  $\{e_1, e_2, \dots, e_{n-1}, \xi\}$  be a local orthonormal basis. Then from (10), we have

$$r = \sum_{i=1}^n \{a\epsilon_i g(e_i, e_i) + b\epsilon_i \eta(e_i)\eta(e_i) + c\epsilon_i g(\phi e_i, e_i)\},$$

where  $\epsilon_i = g(e_i, e_i)$ , which gives (14). □

**Theorem 3.1.** *For an Einstein-like  $\epsilon$ -LP-Sasakian manifold, the scalar curvature  $r$  satisfies the following differential equation*

$$c\xi r + 2br = -2\epsilon(n - 1)[c^2 - b(n + b)].$$

**Proof.** From (10), it follows that the Ricci operator  $Q$  satisfies

$$g(QX, Y) = ag(X, Y) + cg(\phi X, Y) + b\epsilon\eta(X)g(\xi, Y),$$

this implies

$$QX = aX + c\phi X + \epsilon b\eta(X)\xi.$$

Differentiating, we find

$$\begin{aligned} (\nabla_Y Q)X + Q(\nabla_Y X) &= a\nabla_Y X + c(\nabla_Y \phi)X + c\phi(\nabla_Y X) \\ &\quad + \epsilon b(\nabla_Y \eta)(X)\xi + \epsilon b\eta(\nabla_Y X)\xi + \epsilon b\eta(X)\nabla_Y \xi. \end{aligned}$$

Using (5), (6) and (7) in the above equation, we get

$$\begin{aligned} (\nabla_Y Q)X &= c[g(X, Y)\xi + \epsilon\eta(X)Y + 2\epsilon\eta(X)\eta(Y)\xi] \\ &\quad + b[\epsilon g(\phi X, Y)\xi + \eta(X)\phi Y]. \end{aligned}$$

Now, let  $\{e_1, e_2, \dots, e_{n-1}, \xi\}$  be a local orthonormal basis. Multiplying both side by  $\epsilon_i$  in the above equation and contracting with respect to  $Y$ , we have

$$(15) \quad (\operatorname{div} Q)X = \{b(\operatorname{trace}(\phi)) + \epsilon c(n-1)\}\eta(X).$$

From (13) and (14), we get

$$(16) \quad r = c(\operatorname{trace}(\phi)) + \epsilon(n-1)(n+b).$$

Using  $Xr = 2(\operatorname{div} Q)X$  and (16) in (15), we obtain that in an Einstein-like  $\epsilon$ -LP-Sasakian manifold, the scalar curvature  $r$  satisfies the following differential equation

$$(17) \quad c\xi r + 2br = -2\epsilon(n-1)[c^2 - b(n+b)].$$

□

**Theorem 3.2.** *In an Einstein-like  $\epsilon$ -LP-Sasakian manifold, if  $\operatorname{trace}(\phi)$  is constant then*

$$(18) \quad b(\operatorname{trace}(\phi)) = -\epsilon(n-1)c.$$

**Proof.** Using  $Xr = 2(\operatorname{div} Q)X$  in (15), we get

$$(19) \quad dr = 2\{b(\operatorname{trace}(\phi)) + \epsilon c(n-1)\}\eta.$$

Since  $\operatorname{trace}(\phi)$  is constant, then from (14), it follows that  $r$  is constant. Hence (19) gives (18). □

From now, on in this section the  $\operatorname{trace}(\phi)$  will be assumed to be constant.

**Theorem 3.3.** *An  $\epsilon$ -LP-Sasakian manifold with constant trace( $\phi$ ) is Einstein-like if and only if the  $(0, 2)$ -tensor field  $C_1^1(\phi R)$  is a linear combination of  $g$ ,  $\Phi$  and  $\eta \otimes \eta$  formed with constant coefficients.*

**Proof.** Let  $R$  be the curvature tensor in an  $\epsilon$ -LP-Sasakian manifold, we have

$$R(X, Y)\phi Z = \nabla_X \nabla_Y \phi Z - \nabla_Y \nabla_X \phi Z - \nabla_{[X, Y]}\phi Z.$$

Using equations (5), (6) and (7) in the above equation, we have

$$\begin{aligned} (20) \quad R(X, Y)\phi Z &= \phi R(X, Y)Z - \epsilon[\Phi(Y, Z)X - \Phi(X, Z)Y] \\ &\quad + \epsilon[g(Y, Z)\phi X - g(X, Z)\phi Y] \\ &\quad + 2\epsilon[\eta(Y)\Phi(X, Z)\xi - \eta(X)\Phi(Y, Z)\xi] \\ &\quad + 2[\eta(Y)\eta(Z)\phi X - \eta(X)\eta(Z)\phi Y]. \end{aligned}$$

From (20), we have

$$\begin{aligned} (21) \quad 'R(X, Y, \phi Z, W) - 'R(X, Y, Z, \phi W) &= \epsilon[\Phi(X, W)g(Y, Z) - \Phi(Y, W)g(X, Z)] \\ &\quad + \epsilon[\Phi(X, Z)g(Y, W) - g(X, W)\Phi(Y, Z)] \\ &\quad + 2\eta(Z)[\eta(Y)\Phi(X, W) - \eta(X)\Phi(Y, W)] \\ &\quad + 2\eta(W)[\eta(Y)\Phi(X, Z) - \eta(X)\Phi(Y, Z)]. \end{aligned}$$

where  $'R(X, Y, Z, W) = g(R(X, Y)Z, W)$ .

From (21), we have

$$\begin{aligned} (22) \quad 'R(X, Y, \phi Z, \phi W) - 'R(X, Y, Z, W) &= \epsilon[g(\phi X, \phi W)g(\phi Y, \phi Z) - g(\phi X, \phi Z)g(\phi Y, \phi W)] \\ &\quad + \epsilon[\Phi(X, Z)\Phi(Y, W) - \Phi(X, W)\Phi(Y, Z)] \\ &\quad + \eta(Z)[\eta(Y)g(X, W) - \eta(X)g(Y, W)] \\ &\quad + \eta(W)[\eta(X)g(Y, Z) - \eta(Y)g(X, Z)]. \end{aligned}$$

From (22), we have

$$(23) \quad 'R(X, Y, \phi Z, \phi W) = 'R(\phi X, \phi Y, Z, W).$$

Using (22) and (23), we have

$$\begin{aligned} (24) \quad 'R(\phi X, \phi Y, \phi Z, \phi W) = 'R(X, Y, Z, W) &\quad + \eta(Z)[\eta(Y)g(X, W) - \eta(X)g(Y, W)] \\ &\quad + \eta(W)[\eta(X)g(Y, Z) - \eta(Y)g(X, Z)]. \end{aligned}$$

From (24), we have

$$(25) \quad S(\phi Y, \phi Z) = S(Y, Z) + (n - 1)\eta(Y)\eta(Z) \quad \text{and}$$

$$(26) \quad S(Y, \xi) = (n - 1)\eta(Y).$$

Taking  $Z = \phi Z$ , we have

$$(27) \quad S(\phi Y, Z) = S(Y, \phi Z).$$

From (20), we have

$$(28) \quad \begin{aligned} S(Y, \phi Z) &= C_1^1(\phi R)(Y, Z) - \epsilon(n - 2)\Phi(Y, Z) \\ &+ [\epsilon g(Y, Z) + 2\eta(Y)\eta(Z)]\text{trace}(\phi). \end{aligned}$$

Now, from (27), we have in  $\epsilon - LP$ -Sasakian manifold  $S(X, \phi Y) = S(\phi X, Y)$  and also it can be verified that  $C_1^1(\phi R)(Y, Z) = C_1^1(\phi R)(Z, Y)$ ; therefore from this observation relation (28) is consistent.

Now, if the manifold  $M$  is Einstein-like then from (11) and (18), the equation (28) reduces to

$$(29) \quad bC_1^1(\phi R) = c(b + n - 1)g + \epsilon c[b + 2(n - 1)]\eta \otimes \eta + (a + \epsilon(n - 2))\Phi,$$

which shows that  $C_1^1(\phi R)$  is a linear combination of  $g, \Phi$  and  $\eta \otimes \eta$  formed with constant coefficients. The converse is easy to follow.  $\square$

**Corollary 3.1.** *In an Einstein-like  $\epsilon - LP$ -Sasakian manifold with constant trace( $\phi$ ), the  $(0, 2)$ - tensor field  $C_1^1(\phi R)$  is parallel along the vector field  $\xi$ .*

**Proof.** From (5) and (7), we have  $\nabla_\xi \eta = 0$ , and  $\nabla_\xi \phi = 0$ .

Now, in an  $\epsilon - LP$ -Sasakian manifold

$$\begin{aligned} (\nabla_\xi \Phi)(X, Y) &= \nabla_\xi \Phi(X, Y) - \Phi(\nabla_\xi X, Y) - \Phi(X, \nabla_\xi Y) \\ &= g(\nabla_\xi \phi X - \phi \nabla_\xi X, Y) \\ &= g((\nabla_\xi \phi)X, Y) \end{aligned}$$

this implies  $\nabla_\xi \Phi = 0$  for  $\epsilon - LP$ -Sasakian manifold.

Since in an  $\epsilon - LP$ -Sasakian manifold  $\nabla_\xi \Phi = 0$  and  $\nabla_\xi \eta = 0$ , therefore from (29), we conclude that  $C_1^1(\phi R)$  is parallel along the vector field  $\xi$ .  $\square$

**Theorem 3.4.** *In an Einstein-like  $\epsilon - LP$ -Sasakian manifold, we have*

$$(30) \quad L_\xi S = 2a\epsilon\Phi + 2c(\epsilon g + \eta \otimes \eta).$$

**Proof.** In a  $\epsilon - LP$ -Sasakian manifold, we obtain

$$(31) \quad \begin{aligned} (L_\xi \eta)X &= \xi\eta(X) - \eta[\xi, X] \\ &= \xi\eta(X) - \eta(\nabla_\xi X - \nabla_X \xi) \\ &= (\nabla_\xi \eta)X + \eta(\nabla_X \xi) \\ &= 0 \end{aligned}$$

and

$$(32) \quad \begin{aligned} (L_\xi g)(Y, Z) &= \xi g(Y, Z) - g([\xi, Y], Z) - g(Y, [\xi, Z]) \\ &= 2g(\epsilon\phi Y, Z) = 2\epsilon\Phi(Y, Z). \end{aligned}$$

$$(33) \quad \begin{aligned} (L_\xi \Phi)(Y, Z) &= L_\xi g(\phi Y, Z) - \Phi(L_\xi Y, Z) - \Phi(Y, L_\xi Z) \\ &= (L_\xi g)(\phi Y, Z) + g((L_\xi \phi)Y, Z) \\ &= 2\epsilon\Phi(\phi Y, Z) = 2\epsilon g(Y, Z) + 2\eta(Y)\eta(Z) \end{aligned}$$

Thus, we have  $L_\xi \eta = 0$ ,  $L_\xi g = 2\epsilon\Phi$ ,  $L_\xi \phi = 0$  and  $L_\xi \Phi = 2(\epsilon g + \eta \otimes \eta)$ .

Now, taking Lie derivative of  $S$  in the direction of  $\xi$  in (10) and using above results, we obtain (30). □

**Theorem 3.5.** *In an Einstein-like  $\epsilon$ -LP-Sasakian manifold with constant trace( $\phi$ ), we have*

$$(34) \quad L_\xi(C_1^1(\phi R)) = \frac{2\epsilon c}{b}(b+n-1)\Phi + 2\epsilon(a + \epsilon(n-2))(g + \epsilon\eta \otimes \eta)$$

**Proof.** Taking Lie derivative of  $C_1^1(\phi R)$  in the direction of  $\xi$  in (29) and using (31) – (33), we obtain (34). Hence the proof. □

**4.  $\epsilon$ -LP-Sasakian hypersurfaces**

Let  $\widetilde{M}_{n+1}$  be a real  $(n + 1)$  dimensional manifold. Suppose  $\widetilde{M}_{n+1}$  is endowed with an almost product structure  $J$  and a semi-Riemannian metric  $\widetilde{g}$  satisfying

$$(35) \quad \widetilde{g}(J\widetilde{X}, J\widetilde{Y}) = \widetilde{g}(\widetilde{X}, \widetilde{Y}),$$

for all vector fields  $\widetilde{X}, \widetilde{Y}$  in  $\widetilde{M}_{n+1}$ . Then we say that  $\widetilde{M}_{n+1}$  is an indefinite almost product Riemannian manifold. Moreover, if on  $\widetilde{M}_{n+1}$ , we have

$$(36) \quad (\widetilde{\nabla}_{\widetilde{X}} \widetilde{J})\widetilde{Y} = 0,$$

for all  $\widetilde{X}, \widetilde{Y} \in \Gamma(T\widetilde{M}_{n+1})$ , where  $\widetilde{\nabla}$  is the Levi-Civita connection with respect to  $\widetilde{g}$ , we say that  $\widetilde{M}_{n+1}$  is an indefinite locally Riemannian product manifold.

Now, let  $M_n$  be an orientable non-degenerate hypersurface of  $\widetilde{M}_{n+1}$ . Suppose that  $N$  is the unit normal vector field and  $\xi$  is a vector field on  $M_n$  such that

$$(37) \quad \widetilde{g}(N, N) = -\epsilon,$$

$$(38) \quad JN = -\xi.$$

Let

$$(39) \quad JX = \phi X + \eta(X)N, \quad \text{where } X \in \chi(M_n).$$



**Proposition 4.1.** *The set  $(\phi, \xi, \eta, g)$  is an  $\epsilon$ -Lorentzian almost para-contact metric structure, where  $g$  is induced metric on  $M_n$ .*

**Proof.** We have, from (38) and (39),  $X = J^2X = \phi^2X + \eta(\phi X)N - \eta(X)\xi$ .

Equating tangential and normal parts, we get  $\phi^2X = X + \eta(X)\xi$  and  $\eta(\phi X) = 0$ , respectively.

Also, from (38) and (39), we have  $N = J^2N = -J\xi = -\phi\xi - \eta(\xi)N$ ,

Equating tangential and normal parts, we get  $\phi\xi = 0$  and  $\eta(\xi) = -1$ , respectively. Finally, we have  $g(X, Y) = \tilde{g}(JX, JY)$ , where  $X, Y \in M_n$ , which in view of (39) gives (1). Hence the set  $(\phi, \xi, \eta, g)$  is an  $\epsilon$ -Lorentzian almost para-contact metric structure on  $M_n$ . □

The Gauss and Weingarten formulas are given respectively by

$$(40) \quad \tilde{\nabla}_X Y = \nabla_X Y - \epsilon g(AX, Y)N,$$

$$(41) \quad \tilde{\nabla}_X N = -AX,$$

where  $\nabla$  is the Levi-Civita connection with respect to the Riemannian metric  $g$  induced by  $\tilde{g}$  on  $M_n$  and  $A$  is the shape operator of  $M_n$ .

**Proposition 4.2.** *The  $\epsilon$ -Lorentzian almost para-contact metric structure on  $M_n$  satisfies*

$$(42) \quad (\nabla_X \phi)Y = \eta(Y)AX + \epsilon g(AX, Y)\xi,$$

$$(43) \quad (\nabla_X \eta)Y = \epsilon g(AX, \phi Y),$$

$$(44) \quad \nabla_X \xi = \phi AX.$$

**Proof.** Using the equations (38), (39), (40) and (41) in  $(\tilde{\nabla}_X J)Y = 0$ , we get  $(\nabla_X \phi)Y - \eta(Y)AX - \epsilon g(AX, Y)\xi + ((\nabla_X \eta)Y)N - \epsilon g(AX, \phi Y)N = 0$ .

Equating tangential and normal parts, we get (42) and (43), respectively. Equation (42) and (43) implies (44). □

Now, we obtain the following theorems of characterization for  $\epsilon$ -LP-Sasakian hypersurfaces.

**Theorem 4.1.** *Let  $M_n$  be an orientable hypersurfaces of an indefinite locally Riemannian product manifold. Then  $M_n$  is an  $\epsilon$ -LP-Sasakian manifold if and only if the shape operator is given by*

$$(45) \quad A = \epsilon I + \epsilon \eta \otimes \xi.$$

**Proof.** Let  $M_n$  be a  $\epsilon$ -LP-Sasakian manifold. Using (6) and (44), we get

$$(46) \quad AX = \epsilon X + \epsilon \eta(X)\xi - \eta(AX)\xi.$$

In particular, we have  $A\xi = -\eta(A\xi)\xi$ . Thus, we have

$$(47) \quad \eta(AX) = \epsilon g(\xi, AX) = \epsilon g(A\xi, X) = \epsilon g(-\eta(A\xi)\xi, X) = -\eta(A\xi)\eta(X).$$

Using this in (46), we get

$$(48) \quad A = \epsilon I + (\epsilon + \eta(A\xi))\eta \otimes \xi.$$

Using (42) in (48), we have

$$(\nabla_X \phi)Y = \epsilon\eta(Y)\phi X + 2\epsilon\eta(X)\eta(Y)\xi + 2\eta(A\xi)\eta(X)\eta(Y)\xi + g(X, Y)\xi.$$

Using equation (5), we have  $\eta(A\xi)\eta(X)\eta(Y)\xi = 0$ . From above, we have  $\eta(A\xi) = 0$ , which when used in (48) yields (45). Conversely, using (45) in (42) we see that  $M_n$  is  $\epsilon$ -LP-Sasakian manifold.  $\square$

Now, assume that the indefinite almost product Riemannian manifold  $\widetilde{M}_{n+1}$  is of almost constant curvature so that its curvature tensor  $\widetilde{R}$  is given (Yano, 1965) by

$$(49) \quad \begin{aligned} \widetilde{R}(\widetilde{X}, \widetilde{Y}, \widetilde{Z}, \widetilde{W}) &= k\{\widetilde{g}(\widetilde{Y}, \widetilde{Z})\widetilde{g}(\widetilde{X}, \widetilde{W}) - \widetilde{g}(\widetilde{X}, \widetilde{W})\widetilde{g}(\widetilde{Y}, \widetilde{Z}) \\ &\quad + \widetilde{g}(J\widetilde{Y}, \widetilde{Z})\widetilde{g}(J\widetilde{X}, \widetilde{W}) - \widetilde{g}(J\widetilde{X}, \widetilde{Z})\widetilde{g}(J\widetilde{Y}, \widetilde{W})\} \end{aligned}$$

for all vector fields  $\widetilde{X}, \widetilde{Y}, \widetilde{Z}$  and  $\widetilde{W}$  on  $\widetilde{M}_{n+1}$ . If  $M_n$  be a  $\epsilon$ -LP-Sasakian hypersurface, then in view of (45), (49) and the Gauss equation, we have

$$(50) \quad \begin{aligned} R(X, Y, Z, W) &= (k - \epsilon)\{g(Y, Z)g(X, W) - g(X, Z)g(Y, W)\} \\ &\quad + (k)\{g(\phi Y, Z)g(\phi X, W) - g(\phi X, Z)g(\phi Y, W)\} \\ &\quad - g(Y, Z)\eta(X)\eta(W) - g(X, W)\eta(Y)\eta(Z) \\ &\quad + g(X, Z)\eta(Y)\eta(W) + g(Y, W)\eta(X)\eta(Z). \end{aligned}$$

After calculating from (50), we have

$$(51) \quad R(X, Y)\xi = [\epsilon(k - \epsilon) + 1]\{\eta(Y)X - \eta(X)Y\}.$$

Comparing the resulting expression with (8), we find that  $k = \epsilon$ . With this value of  $k$ , from (50), we obtain  $S(Y, Z) = c(\text{trace}(\phi))\Phi(Y, Z) - (n - 1)\eta(Y)\eta(Z)$ . Thus, we have

**Theorem 4.2.** *An  $\epsilon$ -LP-Sasakian hypersurface of an indefinite locally Riemannian product manifold of almost constant curvature ( $k = \epsilon$ ) is always Einstein-like.*

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