

Bach tensor on $N(\kappa)$ -paracontact metric 3-manifolds**K.K. Mirji**

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Abstract. In this paper, we characterize the Bach tensor on $N(\kappa)$ -paracontact metric 3-manifold. It is proved that a $N(\kappa)$ -paracontact metric 3-manifold with purely transversal Bach tensor is of constant scalar curvature 6κ .

Keywords: $N(\kappa)$ -paracontact metric 3-manifold, Cotton tensor, Bach tensor, Scalar curvature.

1. Introduction

The notion of Bach tensor was introduced by Rudolf Bach in [1] when studying so-called conformal relativity. That is, instead of using the Hilbert-Einstein functional, one considers the functional

$$(1) \quad \mathcal{W}(g) = \int_{M^4} |W(g)|^2 dv_g,$$

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for a 4-dimensional compact Riemannian manifolds M , where W denotes the Weyl tensor of type (1, 3) defined by

$$\begin{aligned}
 W(X, Y)Z &= R(X, Y)Z - \frac{1}{2n-1}\{S(Y, Z)X - S(X, Z)Y \\
 &+ g(Y, Z)QX - g(X, Z)QY\} \\
 (2) \quad &+ \frac{r}{2n(2n-1)}\{g(Y, Z)X - g(X, Z)Y\},
 \end{aligned}$$

where R denotes the Riemannian curvature tensor, S is a Ricci tensor and Ricci operator Q is defined by $g(QX, Y) = S(X, Y)$. The Critical points of the functional (1) are characterized by the vanishing of a symmetric trace free (0, 2) type tensor \mathcal{B} is usually referred as Bach tensor and the metric is called Bach flat if \mathcal{B} vanishes. On any Riemannian manifold (M, g) of dimension $(2n + 1)$, the Bach tensor \mathcal{B} is defined by

$$\begin{aligned}
 \mathcal{B}(X, Y) &= \frac{1}{2n-2} \sum_{i,j=1}^{2n+1} ((\nabla_{e_i} \nabla_{e_j} W)(X, e_i, e_j, Y) \\
 (3) \quad &+ \frac{1}{2n-1} \sum_{i,j=1}^{2n+1} S(e_i, e_j)W(X, e_i, e_j, Y),
 \end{aligned}$$

where $\{e_i\}_{i=1}^{2n+1}$ is a local orthonormal frame on (M, g) . A Riemannian manifold M is said to be Einstein if the Ricci tensor S is a constant multiple of the metric tensor g . Now, from (2) and the contraction of Bianchi second identity it follows that $divW = \frac{2n-2}{2n-1}\mathcal{C}$, where \mathcal{C} is the (0, 3)-type Cotton tensor defined by[2]

$$\begin{aligned}
 \mathcal{C}(X, Y)Z &= (\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z) \\
 (4) \quad &- \frac{1}{4n}\{dr(X)g(Y, Z) - dr(Y)g(X, Z)\}.
 \end{aligned}$$

Now, making use of Weyl tensor (2) and Cotton tensor (4), the Bach tensor (3) can be expressed as [3]

$$(5) \quad \mathcal{B}(X, Y) = \frac{1}{2n-1} \left[\sum_{i=1}^{2n+1} (\nabla_{e_i} \mathcal{C})(e_i, X)Y + \sum_{i,j=1}^{2n+1} S(e_i, e_j)W(X, e_i, e_j, Y) \right].$$

In dimension 3, the Weyl tensor W vanishes, and hence the expression of Bach tensor transforms into

$$(6) \quad \mathcal{B}(X, Y) = \sum_{i=1}^3 (\nabla_{e_i} \mathcal{C})(e_i, X)Y.$$

A Riemannian metric g is called Bach flat if the Bach tensor \mathcal{B} of g vanishes. By (3), it is easy to see that Bach flatness is natural generalization of Einstein

and conformal flatness. For more details about Bach tensor, we refer to reader [4, 5, 7, 8] and references therein.

On the other hand, study of nullity distribution on paracontact geometry is one among the most interesting topics in modern paracontact geometry. In 1985, Kaneyuki and Kozai [10] initiated the study of paracontact geometry. The importance of paracontact geometry interplays with the theory of para-Kähler manifolds and its role in pseudo-Riemannian geometry and mathematical physics. A systematic study of paracontact metric manifolds was carried out by Zamkovoy [19]. Further, the study was taken up by many authors, for readers we refer the papers [9, 11, 12, 13, 14, 15, 16, 17, 18, 20] and others.

Recently, Ghosh and Sharma in [6] studied Sasakian manifold with purely transversal Bach tensor. In particular, they proved that if a Sasakian manifold admits a purely transversal Bach tensor, then g has constant scalar curvature $\geq 2n(2n+1)$, with equality holds if and only if g is Einstein, and the Ricci tensor of g has a constant norm. Also, they studied (κ, μ) -contact manifolds with vanishing Bach tensor in [7]. This work turns our attention to study Bach tensor in the framework of certain class of paracontact metric manifolds, particularly, on 3-dimensional $N(\kappa)$ -paracontact metric manifolds (briefly, $N(\kappa)$ -paracontact metric 3-manifolds).

The paper is organized as follows: Section 2 is concerned with the basic formulas and properties of $N(\kappa)$ -paracontact metric manifolds. Section 2 is concerned with the study of $N(\kappa)$ -paracontact metric 3-manifolds with purely transversal Bach tensor. It is proved that a $N(\kappa)$ -paracontact metric 3-manifold with purely transversal Bach tensor is of constant scalar curvature.

2. Preliminaries

An almost paracontact structure on a $(2n+1)$ -dimensional smooth manifold M^{2n+1} is a triplet (ϕ, ξ, η) , where ϕ is a $(1, 1)$ -type tensor field, ξ is a vector field called the Reeb vector field and η is a 1-form such that:

- (i) $\phi^2 X = X - \eta(X)\xi$,
- (ii) $\phi(\xi) = 0, \eta \cdot \phi = 0, \eta(\xi) = 1$,
- (iii) the tensor field ϕ induces an almost paracomplex structure on each fibre of $\mathcal{D} = \ker(\eta)$, that is, the eigendistributions \mathcal{D}_ϕ^+ and \mathcal{D}_ϕ^- of ϕ corresponding to the eigenvalues 1 and -1, respectively, have same dimension n .

An almost paracontact manifold equipped with a pseudo-Riemannian metric g such that

$$(7) \quad g(\phi X, \phi Y) = -g(X, Y) + \eta(X)\eta(Y),$$

for all $X, Y \in \chi(M)$, is called almost paracontact metric manifold and (ϕ, ξ, η, g) is said to be an almost paracontact metric structure. An almost paracontact structure is normal [30] if and only if the $(1, 2)$ -type torsion tensor $N_\phi = [\phi, \phi] - 2d\eta \otimes \xi = 0$, where $[\phi, \phi](X, Y) = \phi^2[X, Y] - [\phi, \phi]$. An almost paracontact structure is called a paracontact structure if $g(X, \phi Y) = d\eta(X, Y)$

[20]. Any almost paracontact metric manifold $(M^{2n+1}, \varphi, \xi, \eta, g)$ admits a φ basis [20], that is, a pseudo-orthonormal basis of vector fields of the form $\xi, E_1, E_2, \dots, E_n, \varphi E_1, \varphi E_2, \dots, \varphi E_n$, where $\xi, E_1, E_2, \dots, E_n$ are space-like vector fields and then, by (2.1) the vector fields $\varphi E_1, \varphi E_2, \dots, \varphi E_n$ are time-like. For a three-dimensional almost paracontact metric manifold, any (local) pseudo-orthonormal basis of $\ker(\eta)$ determines a φ -basis, up to sign. If e_2, e_3 is a (local) pseudo-orthonormal basis of $\ker(\eta)$, with e_3 , time-like, so by (7) vector field $\varphi e_2 \in \ker(\eta)$ is time-like and orthogonal to e_2 . Therefore, $\varphi e_2 = \pm e_3$ and $\xi, e_2, \pm e_3$ is a φ -basis [13]. In a paracontact metric manifold, one can introduce a symmetric, trace-free (1, 1)-tensor $h = \frac{1}{2}\mathcal{L}_\xi\varphi$ such that $\varphi h + h\varphi = 0$ and $h\xi = 0$ satisfying [12, 16, 19, 20]

$$\begin{aligned} (8) \quad & \nabla_X\xi = -\varphi X + \varphi hX, \\ (9) \quad & (\nabla_X\eta)Y = g(X - hX, \varphi Y), \\ (10) \quad & (\nabla_X\varphi)Y = -g(X - hX, Y)\xi + \eta(Y)(X - hX), \end{aligned}$$

for any $X, Y \in \chi(M)$. Note that, the condition $h = 0$ is equivalent to ξ being Killing vector field and then (φ, ξ, η, g) is said to be K -paracontact structure. A paracontact metric manifold is said to be a (κ, μ) -paracontact metric manifold if the curvature tensor R satisfies

$$(11) \quad R(X, Y)\xi = \kappa(\eta(Y)X - n(X)Y) + \mu(\eta(Y)hX - n(X)hY),$$

for all vector fields $X, Y \in \chi(M)$ and κ, μ are real constants. In particular, if $\mu = 0$, then the (κ, μ) -paracontact metric manifold reduces to an $N(\kappa)$ -paracontact metric manifold. Thus, for an $N(\kappa)$ -paracontact metric manifold the Riemannian curvature tensor R satisfies

$$(12) \quad R(X, Y)\xi = \kappa(\eta(Y)X - n(X)Y).$$

In a 3-dimensional $N(\kappa)$ -paracontact metric manifold $(M^3, \varphi, \xi, \eta, g)$, the following relations hold [14]:

$$\begin{aligned} (13) \quad & QX = \left(\frac{r}{2} - \kappa\right)X + \left(3\kappa - \frac{r}{2}\right)\eta(X)\xi, \\ (14) \quad & S(X, Y) = \left(\frac{r}{2} - \kappa\right)g(X, Y) + \left(3\kappa - \frac{r}{2}\right)\eta(X)\eta(Y), \\ (15) \quad & S(X, \xi) = 2\kappa\eta(X), \\ (16) \quad & Q\xi = 2\kappa\xi, \end{aligned}$$

for all vector fields $X, Y \in \chi(M)$, where Q and S are the Ricci operator and the Ricci tensor, respectively.

The covariant differentiation of (14) along any arbitrary vector field Z gives

$$\begin{aligned} (\nabla_Z S)(X, Y) &= \frac{dr(Z)}{2}[g(X, Y) - \eta(X)\eta(Y)] \\ &+ \left(3\kappa - \frac{r}{2}\right)[(\nabla_Z\eta)(Y)\eta(X) + (\nabla_Z\eta)(X)\eta(Y)]. \end{aligned}$$

Making use of (9) and replacing X by φX in above relation, we obtain

$$(17) \quad \begin{aligned} (\nabla_Z S)(\varphi X, Y) &= \frac{dr(Z)}{2} [g(\varphi X, Y) - \eta(X)\eta(Y)] \\ &+ \left(3\kappa - \frac{r}{2}\right) [g(Z - hZ, X)\eta(Y) - \eta(X)\eta(Y)\eta(Z)]. \end{aligned}$$

In an orthogonal frame field $\{e_i\}_{i=1}^3$ of tangent space M , setting $X = Z = e_i$ in (17) and taking summation over i and then using a fact that $Tr(h) = 0$, we get

$$(18) \quad \begin{aligned} \sum_{i=1}^3 (\nabla_{e_i} S)(\varphi e_i, Y) &= \sum_{i=1}^3 g((\nabla_{e_i} Q)\varphi e_i, Y) \\ &= (6\kappa - r)\eta(Y) - \frac{1}{2} dr(\varphi Y). \end{aligned}$$

Again, setting $X = Y = e_i$ in (17) and taking summation over i and then using the fact that $Tr(\varphi) = 0, h\xi = 0$, we get

$$(19) \quad \sum_{i=1}^3 (\nabla_Z S)(\varphi e_i, e_i) = \sum_{i=1}^3 g((\nabla_Z Q)\varphi e_i, e_i) = 0.$$

Next, replacing X by hX in the relation (17), we obtain

$$(20) \quad (\nabla_Z S)(\varphi hX, Y) = \frac{dr(Z)}{2} g(\varphi hX, Y) + \left(3\kappa - \frac{r}{2}\right) g(Z - hZ, hX)\eta(Y).$$

Taking $X = Z = e_i$ in (20) and taking summation over i and then using a fact that $Tr(h) = Tr(h^2) = 0$, we get

$$(21) \quad \sum_{i=1}^3 (\nabla_{e_i} S)(\varphi h e_i, Y) = \sum_{i=1}^3 g((\nabla_{e_i} Q)\varphi h e_i, Y) = \frac{1}{2} dr(\varphi h Y).$$

Also, by setting $X = Y = e_i$ and taking summation over i and then using the fact that $Tr(\varphi h) = 0, h\xi = 0$, we obtain

$$(22) \quad \sum_{i=1}^3 (\nabla_Z S)(\varphi h e_i, e_i) = \sum_{i=1}^3 g((\nabla_Z Q)\varphi h e_i, e_i) = 0.$$

Now, we recall some results on 3-dimensional $N(\kappa)$ -paracontact metric manifolds which will be useful for the next section:

Lemma 2.1 ([14]). *An $N(\kappa)$ -paracontact metric 3-manifold $(M^3, \varphi, \xi, \eta, g)$ is locally φ -symmetric if and only if the scalar curvature r of g is constant.*

Lemma 2.2 ([18]). *On any $N(\kappa)$ -paracontact metric 3-manifold $\xi r = 0$.*

3. Bach tensor on $N(\kappa)$ -paracontact metric 3-manifolds

In this section, we aim to study $N(\kappa)$ -paracontact metric 3-manifold with purely transversal Bach tensor, i.e., $\mathcal{B}(X, \xi) = 0$. First, we present the following result:

Lemma 3.1. *For a $N(\kappa)$ -paracontact metric 3-manifold M^3 , the following relation hold:*

$$\begin{aligned}
 \sum_{i=1}^3 (\nabla_{e_i} \mathcal{C})(e_i, Y)\xi &= 3(6\kappa - r)\eta(Y) - \frac{3}{2}dr(\varphi Y) - \frac{1}{2}dr(\varphi hY) \\
 &+ \sum_{i=1}^3 g((\nabla_{e_i} \varphi h)Y, Qe_i) - \sum_{i=1}^3 g((\nabla_{e_i} \varphi h)e_i, QY) \\
 (23) \qquad &- \frac{1}{4}g(\nabla_{\xi} Dr, Y).
 \end{aligned}$$

Proof. In a 3-dimensional manifold (M^3, g) , for $X, Y, Z \in \chi(M)$ the Cotton tensor is given by

$$\begin{aligned}
 \mathcal{C}(X, Y)Z &= (\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z) \\
 (24) \qquad &- \frac{1}{4}\{dr(X)g(Y, Z) - dr(Y)g(X, Z)\}.
 \end{aligned}$$

Replacing Z by ξ in (24), we get

$$\begin{aligned}
 \mathcal{C}(X, Y)\xi &= (\nabla_X S)(Y, \xi) - (\nabla_Y S)(X, \xi) \\
 (25) \qquad &- \frac{1}{4}\{dr(X)\eta(Y) - dr(Y)\eta(X)\}.
 \end{aligned}$$

Differentiating covariantly (16) along an arbitrary vector field X , we obtain

$$(26) \qquad (\nabla_X Q)\xi = 2\kappa\nabla_X \xi - Q\nabla_X \xi.$$

Using (8) in the above equation, we get

$$(27) \qquad (\nabla_X Q)\xi = -2\kappa(\varphi X - \varphi hX) + Q(\varphi X - \varphi hX).$$

Take an inner product of (27) with respect to vector field Y , we obtain

$$\begin{aligned}
 g((\nabla_X Q)\xi, Y) = (\nabla_X S)(Y, \xi) &= -2\kappa g(\varphi X - \varphi hX, Y) \\
 (28) \qquad &+ g(\varphi X - \varphi hX, QY).
 \end{aligned}$$

Making use of (28) in (25) shows that

$$\begin{aligned}
 \mathcal{C}(X, Y)\xi &= -4\kappa g(\varphi X, Y) + 2g(Q\varphi X, Y) - g(Q\varphi hX, Y) + g(Q\varphi hY, X) \\
 (29) \qquad &- \frac{1}{4}[dr(X)\eta(Y) - dr(Y)\eta(X)].
 \end{aligned}$$

Taking covariant differentiation of $\mathcal{C}(X, Y)\xi$ along an arbitrary vector field W , we get

$$(30) \quad \begin{aligned} (\nabla_W \mathcal{C})(X, Y)\xi &= \nabla_W \mathcal{C}(X, Y)\xi - \mathcal{C}(\nabla_W X, Y)\xi \\ &- \mathcal{C}(X, \nabla_W Y)\xi - \mathcal{C}(X, Y)\nabla_W \xi. \end{aligned}$$

Using (27) and (29) in (30), we deduce

$$\begin{aligned} (\nabla_W \mathcal{C})(X, Y)\xi &= \mathcal{C}(X, Y)\varphi W - \mathcal{C}(X, Y)\varphi hW - 4\kappa g((\nabla_W \varphi)X, Y) \\ &+ 2[g((\nabla_W Q)\varphi X, Y) + g(Q(\nabla_W \varphi)X, Y)] \\ &- g((\nabla_W Q)\varphi hX, Y) - g(Q(\nabla_W \varphi h)X, Y) \\ &+ g((\nabla_W Q)\varphi hY, X) + g(Q(\nabla_W \varphi h)Y, X) \\ &- \frac{1}{4}[dr(X)(\nabla_W \eta)(Y) - dr(Y)(\nabla_W \eta)(X) \\ &- g(\nabla_W Dr, X)\eta(Y) + g(\nabla_W Dr, Y)\eta(X)]. \end{aligned}$$

From the relation (9), (10) and (24) above equation becomes

$$(31) \quad \begin{aligned} (\nabla_W \mathcal{C})(X, Y)\xi &= (\nabla_X S)(Y, \varphi W) - (\nabla_Y S)(X, \varphi W) - (\nabla_X S)(Y, \varphi hW) \\ &+ (\nabla_Y S)(X, \varphi hW) - 4\kappa g(W - hW, Y)\eta(X) \\ &+ 2g(W - hW, QY)\eta(X) + 2g((\nabla_W Q)\varphi X, Y) \\ &- g((\nabla_W Q)\varphi hX, Y) - g(Q(\nabla_W \varphi h)X, Y) \\ &+ g((\nabla_W Q)\varphi hY, X) + g(Q(\nabla_W \varphi h)Y, X) \\ &+ \frac{1}{4}[g(\nabla_W Dr, X)\eta(Y) - g(\nabla_W Dr, Y)\eta(X)]. \end{aligned}$$

Setting $X = W = e_i$ in (31) and summing over i and then use of the relations (18), (19), (21) and (22) proves our lemma. \square

Now, we state and prove the main result of this paper:

Theorem 3.1. *If an $N(\kappa)$ -paracontact metric 3-manifold M^3 with $\kappa > -1$ has purely transversal Bach tensor, then the scalar curvature r is constant.*

Proof. In an $N(\kappa)$ -paracontact metric 3-manifold with $\kappa > -1$, we have

$$(32) \quad \begin{aligned} (\nabla_X \varphi h)Y &= (1 + \kappa)[g(X, Y)\xi - \eta(X)\eta(Y)\xi] - g(hX, Y)\xi \\ &+ (1 + \kappa)\eta(Y)[X - \eta(X)\xi] - \eta(Y)hX. \end{aligned}$$

Taking an inner product of (32) with respect to QZ , we get

$$(33) \quad \begin{aligned} g((\nabla_X \varphi h)Y, QZ) &= 2\kappa(1 + \kappa)[g(X, Y)\eta(Z) - 2\eta(X)\eta(Y)\eta(Z)] \\ &- 2\kappa g(hX, Y)\eta(Z) + (1 + \kappa)g(X, QZ)\eta(Y) \\ &- g(hX, QZ)\eta(Y). \end{aligned}$$

Take an orthogonal frame field $\{e_i\}$, $i = 1, 2, 3$ of tangent space M^3 , setting $X = Y = e_i$ in (33) and then summing over i , we obtain

$$(34) \quad \sum_{i=1}^3 g((\nabla_{e_i} \varphi h)e_i, QZ) = 4\kappa(1 + \kappa)\eta(Z).$$

Again, take an orthogonal frame field $\{e_i\}$, $i = 1, 2, 3$ of tangent space M^3 , setting $X = Z = e_i$ in (33) and then summing over i gives

$$(35) \quad \sum_{i=1}^3 g((\nabla_{e_i} \varphi h)Y, Qe_i) = (1 + \kappa)(r - 2\kappa)\eta(Y).$$

Replacing Z by Y , in (34) and subtracting it in (35), gives

$$(36) \quad \sum_{i=1}^3 g((\nabla_{e_i} \varphi h)Y, Qe_i) - \sum_{i=1}^3 g((\nabla_{e_i} \varphi h)e_i, QY) = (1 + \kappa)(r - 6\kappa)\eta(Y).$$

Making use of (36) in (23) yields

$$(37) \quad \begin{aligned} \sum_{i=1}^3 (\nabla_{e_i} \mathcal{C})(e_i, Y)\xi &= (6\kappa - r)(2 - \kappa)\eta(Y) - \frac{3}{2}dr(\varphi Y) \\ &- \frac{1}{2}dr(\varphi hY) - \frac{1}{4}g(\nabla_\xi Dr, Y). \end{aligned}$$

By employing (37) in (6), we obtain

$$(38) \quad g(\nabla_\xi Dr, Y) = 4(6\kappa - r)(2 - \kappa)\eta(Y) - 6dr(\varphi Y) - 2dr(\varphi hX).$$

Replacing Y by φY in the above equation and simplification leads the following

$$(39) \quad \nabla_\xi Dr = (6 + 2h)\varphi Dr.$$

From Lemma 2.2, we get $dr(\xi) = 0$ implies that $\nabla_\xi Dr = 0$. Therefore from above relation we get

$$(40) \quad (6 + 2h)\varphi Dr = 0,$$

which implies that $\varphi Dr = 0$. If $\varphi Dr = 0$, then $Dr = 0$, which shows that r is constant. This proves the theorem. \square

From the Lemma 2.1 and Theorem 3.1, we have the following:

Corollary 3.1. *A 3-dimensional $N(\kappa \neq -1)$ -paracontact metric manifold M^3 with purely transversal Bach tensor is locally φ -symmetric.*

Following the proof of the above theorem 3.1, we are in a position to prove

Corollary 3.2. *If an $N(\kappa)$ -paracontact metric 3-manifold M^3 with $\kappa > -1$ has purely transversal Bach tensor, then the scalar curvature r is equal to 6κ .*

Proof. Since M^3 is a $N(\kappa)$ -paracontact metric 3-manifold with $\kappa > -1$ and has a purely transversal Bach tensor. we have from Theorem 3.1 and (38) that

$$(41) \quad 4(6\kappa - r)(2 - \kappa)\eta(Y) = 0.$$

This gives $r = 6\kappa$. □

Theorem 3.2. *An $N(\kappa)$ -paracontact metric 3-manifold M^3 with $\kappa > -1$ has purely transversal Bach tensor if and only if the manifold M^3 is of constant scalar curvature $r = 6\kappa$.*

Proof. Let M^3 be an $N(\kappa)$ -paracontact metric 3-manifold with $\kappa > -1$ has constant scalar curvature $r = 6\kappa$. Then from (37) we get

$$\sum_{i=1}^3 (\nabla_{e_i} \mathcal{C})(e_i, Y)\xi = 0$$

which intern gives from (6) that $\mathcal{B}(Y, \xi) = 0$. That is, the manifold M^3 has purely transversal Bach tensor. The converse is obvious from Theorem 3.1 and Corollary 3.2. □

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